

Multi-Time Lagrange Spaces

Irena Čomić

Abstract

M. Neagu and C. Udriste in [6]-[9] introduced and studied the multi-time Lagrange spaces supplied with d -connection. V. Balan in [2] and [3] examined geodesics, paths, Jacobi fields in these spaces. Here the connection is generalized and the relations for torsion and curvature tensors appear in widely achieved form. The introduced notation help us to write that complicated expressions in simpler form.

M.S.C. 2000: 53B40, 53C60.

Key words: generalized multi-time Lagrange spaces, torsion tensors, curvature tensors

1. Adapted bases

Let E be a $n + p + np$ dimensional C^∞ manifold. Some point u of E in some local chart (U, φ) has coordinates

$$(x^i, t^\alpha, x_\alpha^i), \quad i, j, k, \dots = \overline{1, n}, \quad \alpha, \beta, \gamma, \delta, \dots = \overline{1, p}.$$

If in some other chart (U', φ') the same point u has coordinates $(x^{i'}, t^{\alpha'}, x_{\alpha'}^{i'})$, then the allowable coordinate transformations are given by

$$(1.1) \quad \begin{aligned} x^{i'} &= x^{i'}(x^i) \Leftrightarrow x^i = x^i(x^{i'}) \\ t^{\alpha'} &= t^{\alpha'}(t^\alpha) \Leftrightarrow t^\alpha = t^\alpha(t^{\alpha'}) \\ x_{\alpha'}^{i'} &= B_i^{i'} B_{\alpha'}^\alpha x_\alpha^i, \quad B_i^{i'} = \frac{\partial x^{i'}}{\partial x^i}, \quad B_{\alpha'}^\alpha = \frac{\partial t^\alpha}{\partial t^{\alpha'}}. \end{aligned}$$

The transformations of (1.1) are regular, so exist inverse transformations and we have

$$(1.2) \quad B_i^{i'} B_{j'}^i = \delta_{j'}^{i'}, \quad B_{i'}^i B_j^{i'} = \delta_j^i, \quad B_{\alpha'}^\alpha B_{\beta'}^\alpha = \delta_{\beta'}^\alpha, \quad B_\alpha^\alpha B_{\beta'}^\alpha = \delta_\beta^\alpha.$$

Theorem 1.1. *The transformations of type (1.1) form a pseudo-group.*

The natural basis \bar{B} of $T(E)$ is

$$(1.3) \quad \bar{B} = \left\{ \partial_i = \frac{\partial}{\partial x^i}, \partial_\alpha = \frac{\partial}{\partial t^\alpha} \quad \partial_i^\alpha = \frac{\partial}{\partial x_\alpha^i} \right\}.$$

Under coordinate transformation (1.1) the elements of \bar{B} are transforming in the following way:

$$(1.4) \quad \begin{aligned} \partial_{i'} &= B_{i'}^i \partial_i + B_{j' i'}^i B_{\alpha'}^{\alpha'} x_{\alpha'}^{j'} \partial_i^\alpha \\ \partial_{\alpha'} &= B_{\alpha'}^\alpha \partial_\alpha + B_{i'}^i B_{\alpha' \beta}^{\gamma'} B_{\alpha'}^\beta x_{\gamma'}^{i'} \partial_i^\alpha \\ \partial_{i'}^{\alpha'} &= B_{\alpha'}^{\alpha'} B_{i'}^i \partial_i^\alpha. \end{aligned}$$

The above equation in the matrix form can be written as follows

$$(1.5) \quad [\partial_{i'} \partial_{\alpha'} \partial_{i'}^{\alpha'}] = [\partial_i \partial_\alpha \partial_i^\alpha] \cdot \begin{bmatrix} B_{i'}^i & 0 & 0 \\ 0 & B_{\alpha'}^\alpha & 0 \\ B_{j' i'}^i B_{\alpha'}^{\alpha'} x_{\alpha'}^{j'} & B_{i'}^i B_{\alpha' \beta}^{\gamma'} B_{\alpha'}^\beta x_{\gamma'}^{i'} & B_{i'}^i B_{\alpha'}^{\alpha'} \end{bmatrix}$$

The natural basis \bar{B}^* of $T^*(E)$ is

$$(1.6) \quad \bar{B}^* = \{dx^i, dt^\alpha, dx_\alpha^i\}.$$

Under coordinate transformation (1.1) the elements of \bar{B}^* are transforming as follows

$$(1.7) \quad \begin{aligned} dx^{i'} &= B_{i'}^i dx^i \\ dt^{\alpha'} &= B_{\alpha'}^\alpha dt^\alpha \\ dx_{\alpha'}^{i'} &= B_{j' i'}^i B_{\alpha'}^\alpha x_\alpha^j dx^i + B_{i'}^i B_{\alpha' \beta}^{\gamma'} B_{\alpha'}^{\beta'} x_{\gamma'}^i dt^\alpha + B_{i'}^i B_{\alpha'}^\alpha dx_\alpha^i. \end{aligned}$$

(1.7) in the matrix form is given by following relation

$$(1.8) \quad \begin{bmatrix} dx^{i'} \\ dt^{\alpha'} \\ dx_{\alpha'}^{i'} \end{bmatrix} = \begin{bmatrix} B_{i'}^i & 0 & 0 \\ 0 & B_{\alpha'}^\alpha & 0 \\ B_{j' i'}^i B_{\alpha'}^\alpha x_\alpha^j & B_{i'}^i B_{\alpha' \beta}^{\gamma'} B_{\alpha'}^{\beta'} x_{\gamma'}^i & B_{i'}^i B_{\alpha'}^\alpha \end{bmatrix} \begin{bmatrix} dx^i \\ dt^\alpha \\ dx_\alpha^i \end{bmatrix}$$

Theorem 1.2. *The duality of \bar{B}^* to \bar{B} is coordinate invariant.*

Proof. Let us suppose that

$$(1.9) \quad \begin{bmatrix} dx^i \\ dt^\alpha \\ dx_\alpha^i \end{bmatrix} [\partial_k \partial_\gamma \partial_k^\gamma] = \begin{bmatrix} \delta_k^i & 0 & 0 \\ 0 & \delta_\gamma^\alpha & 0 \\ 0 & 0 & \delta_\alpha^\gamma \delta_k^i \end{bmatrix}$$

then using (1.8), (1.9) and (1.4) we have

$$\begin{aligned}
& \begin{bmatrix} dx^{i'} \\ dt^{\alpha'} \\ dx^{\alpha'} \end{bmatrix} [\partial_{k'} \partial_{\gamma'} \partial_{k'}^{\gamma'}] = \\
& \begin{bmatrix} B_i^{i'} & 0 & 0 \\ 0 & B_{\alpha'}^{\alpha'} & 0 \\ B_{j' i'} B_{\alpha'}^{\alpha'} x_{\alpha}^j & B_i^{i'} B_{\alpha'}^{\gamma'} B_{\beta'}^{\beta'} B_{\alpha}^{\beta'} x_{\gamma}^i & B_i^{i'} B_{\alpha'}^{\alpha} \end{bmatrix} \begin{bmatrix} \delta_k^i & 0 \\ 0 & \delta_{\gamma}^{\alpha} & 0 \\ 0 & 0 & \delta_{\alpha}^{\gamma} \delta_k^i \end{bmatrix} \cdot \\
& \begin{bmatrix} B_{k'}^k & 0 \\ 0 & B_{\gamma'}^{\gamma} \\ B_{h' k'} B_{\gamma'}^{\gamma} x_{\gamma'}^{k'} & B_{k'}^k B_{\alpha'}^{\delta'} B_{\gamma'}^{\kappa} x_{\delta'}^{k'} & B_{k'}^k B_{\gamma'}^{\gamma} \end{bmatrix} = \\
& \begin{bmatrix} B_i^{i'} & 0 & 0 \\ 0 & B_{\alpha'}^{\alpha'} & 0 \\ B_{j' i'} B_{\alpha'}^{\gamma} x_{\gamma}^j & B_i^{i'} B_{\alpha'}^{\gamma} B_{\beta'}^{\beta'} B_{\alpha}^{\beta'} x_{\gamma}^i & B_i^{i'} B_{\alpha'}^{\alpha} \end{bmatrix} \begin{bmatrix} B_{k'}^{i'} & 0 & 0 \\ 0 & B_{\gamma'}^{\alpha} & 0 \\ B_{h' k'} B_{\alpha'}^{\gamma} x_{\gamma'}^{h'} & B_{k'}^i B_{\alpha'}^{\delta'} B_{\gamma'}^{\kappa} x_{\delta'}^{k'} & B_{k'}^i B_{\alpha'}^{\gamma} \end{bmatrix} \\
& = \begin{bmatrix} \delta_{k'}^{i'} & 0 \\ 0 & \delta_{\gamma'}^{\alpha'} & 0 \\ \bar{A} & \bar{B} & \delta_{k'}^{i'} \delta_{\alpha'}^{\gamma'} \end{bmatrix},
\end{aligned}$$

where

$$(1.10) \quad \bar{A} = B_{j' i'} B_{k'}^i B_{\alpha'}^{\alpha} x_{\alpha}^j + B_i^{i'} B_{\alpha'}^{\alpha} B_{h' k'}^i B_{\alpha'}^{\gamma'} x_{\gamma'}^{h'}$$

$$(1.11) \quad \bar{B} = B_i^{i'} B_{\alpha'}^{\gamma} B_{\delta'}^{\delta'} x_{\gamma}^i B_{\gamma'}^{\alpha} + B_i^{i'} B_{\alpha'}^{\alpha} B_{k'}^i B_{\alpha'}^{\delta'} B_{\gamma'}^{\kappa} x_{\delta'}^{k'}.$$

From $B_i^{i'} B_{k'}^i = \delta_{k'}^{i'}$ it follows

$$(1.12) \quad B_{i' j} B_{k'}^i + B_i^{i'} B_{k' j'} B_j^{j'} = 0.$$

The substitution of the above equation into \bar{A} results

$$(1.13) \quad \bar{A} = -B_i^{i'} B_{k'}^i B_{j'}^{j'} B_j^{j'} B_{\alpha'}^{\alpha} x_{\alpha}^j + B_i^{i'} B_{\alpha'}^{\alpha} B_{j' k'}^i B_{\alpha'}^{\gamma'} x_{\gamma'}^{j'}.$$

From (1.1) and (1.2) it follows that

$$x_{\gamma'}^{j'} B_{\alpha'}^{\gamma'} = B_j^{j'} B_{\gamma'}^{\gamma} B_{\alpha}^{\gamma} x_{\gamma}^j = B_j^{j'} \delta_{\alpha}^{\gamma} x_{\gamma}^j = B_j^{j'} x_{\alpha}^j,$$

which together with (1.12) gives

$$(1.14) \quad \bar{A} = 0.$$

As $B_{\delta'}^{\gamma} B_{\kappa}^{\delta'} = \delta_{\kappa}^{\gamma}$ we have

$$(1.15) \quad B_{\delta'}^{\gamma} B_{\alpha'}^{\delta'} B_{\kappa}^{\delta'} + B_{\delta'}^{\gamma} B_{\kappa}^{\delta'} B_{\alpha'}^{\alpha} = 0.$$

(1.1) and the substitution of the above equation into (1.11) result:

$$\begin{aligned}
\bar{B} &= -B_i^{i'} B_{\delta'}^{\gamma} B_{\kappa}^{\delta'} B_{\alpha}^{\alpha} x_{\gamma}^i B_{\gamma'}^{\kappa} + \\
& B_i^{i'} B_{\alpha'}^{\alpha} B_{k'}^i B_{\alpha'}^{\delta'} B_{\gamma'}^{\kappa} x_{\delta'}^{k'},
\end{aligned}$$

i.e.

$$(1.16) \quad \bar{B} = B_{\kappa}^{\delta'} B_{\alpha}^{\alpha} B_{\gamma'}^{\kappa} (-x_{\delta'}^{i'} + x_{\delta'}^{i'}) = 0 \quad \square.$$

Definition 1.1. *The adapted basis*

$$B = \{\delta_i, \delta_{\alpha} \delta_i^{\alpha}\}$$

of $T(E)$ is given by

$$(1.17) \quad \begin{aligned} \delta_i &= \partial_i - N_{i\beta}^k \partial_k^{\beta} \\ \delta_{\alpha} &= \partial_{\alpha} - M_{\alpha\beta}^k \partial_k^{\beta} \\ \delta_i^{\alpha} &= \partial_i^{\alpha}. \end{aligned}$$

We want, that elements of the adapted basis B under (1.1) transform as tensors i.e.

$$(1.18) \quad \delta_{i'} = B_{i'}^i \delta_i, \quad \delta_{\alpha'} = B_{\alpha'}^{\alpha} \delta_{\alpha}, \quad \delta_{i'}^{\alpha'} = B_{\alpha'}^{\alpha} B_{i'}^i \delta_i^{\alpha}.$$

Theorem 1.3. *The elements of the adapted basis B of $T(E)$ are transforming as tensors (i.e satisfy (1.18)), when the functions $N_{j\beta}^k$ and $M_{\alpha\beta}^k$ satisfy (1.19) and (1.20):*

$$(1.19) \quad N_{j\beta}^k = N_{j'\beta'}^{k'} B_j^{j'} B_{k'}^k B_{\beta}^{\beta'} + B_{h'}^k B_{h'}^{k'} x_{\beta}^h$$

$$(1.20) \quad M_{\alpha\beta}^k = M_{\alpha'\beta'}^{k'} B_{\alpha}^{\alpha'} B_{k'}^k B_{\beta}^{\beta'} + B_{\alpha'\beta'}^{\gamma} B_{\alpha}^{\alpha'} B_{\gamma}^{\beta'} x_{\beta}^k.$$

Proof. If we substitute (1.17) into (1.18) we get

$$(1.21) \quad N_{i\beta}^k B_{i'}^i = N_{i'\beta'}^{k'} B_{\beta}^{\beta'} B_{k'}^k - B_{j'\beta'}^k B_{\beta}^{\beta'} x_{\alpha'}^{j'}.$$

$$(1.22) \quad M_{\alpha\beta}^k B_{\alpha'}^{\alpha} = M_{\alpha'\beta'}^{k'} B_{\beta}^{\beta'} B_{k'}^k - B_{i'\beta'}^k B_{\beta}^{\beta'} B_{\alpha'}^{\alpha} x_{\gamma'}^{i'}.$$

From (1.12) and (1.15) we obtain

$$(1.23) \quad -B_{j'\beta'}^k B_{\beta}^{\beta'} x_{\alpha'}^{j'} = B_{j'}^k B_{h'}^{j'} B_{i'}^h x_{\beta}^h.$$

$$(1.24) \quad -B_{i'\beta'}^k B_{\beta}^{\beta'} B_{\alpha'}^{\alpha} x_{\gamma'}^{i'} = B_{\alpha'\beta'}^{\gamma} x_{\beta}^k B_{\gamma}^{\beta'}.$$

The substitution of (1.23) into (1.21) gives (1.19) and the substitution of (1.24) into (1.22) results (1.20).

Definition 1.2. *The adapted basis*

$$(1.25) \quad B^* = \{\delta x^i, \delta t^{\alpha}, \delta x_{\alpha}^i\}$$

of $T^*(E)$ is given by

$$(1.26) \quad \begin{aligned} \delta x^i &= dx^i, \quad \delta t^{\alpha} = dt^{\alpha} \\ \delta x_{\alpha}^i &= dx_{\alpha}^i + M_{\alpha\beta}^i dt^{\beta} + N_{\alpha j}^i dx^j. \end{aligned}$$

The transformation on law of functions $M_{\alpha\beta}^i$ and $N_{\alpha j}^i$ should be determined in such a way that δx^i , δt^α , δx_α^i transform as tensors, i.e

$$(1.27) \quad \delta x^{i'} = B_i^{i'} \delta x^i, \quad \delta t^{\alpha'} = B_\alpha^{\alpha'} \delta t^\alpha, \quad \delta x_{\alpha'}^i = B_i^{i'} B_\alpha^{\alpha'} x_\alpha^i.$$

Theorem 1.4. *The elements of the adapted basis B^* of $T^*(E)$ are transforming as tensors, when the functions $N_{\alpha j}^i$, $M_{\alpha\beta}^i$ satisfy (1.28) and (1.29)*

$$(1.28) \quad N_{\beta i}^k = N_{\beta' i'}^{k'} B_i^{i'} B_{k'}^k B_\beta^{\beta'} + B_{j i}^{k'} B_{k'}^k x_\beta^j.$$

$$(1.29) \quad M_{\beta\alpha}^k = M_{\beta\alpha'}^{k'} B_\alpha^{\alpha'} B_{k'}^k B_\beta^{\beta'} + B_{\beta'\alpha'}^\gamma B_\beta^{\beta'} B_\alpha^{\alpha'} x_\gamma^k.$$

Proof. The substitution of (1.26) into (1.27) gives

$$(1.30) \quad N_{\alpha i}^j B_\alpha^{\alpha'} B_j^{i'} = N_{\alpha' j'}^{i'} B_i^{i'} + B_{j i}^{i'} B_\alpha^{\alpha'} x_\alpha^j.$$

$$(1.31) \quad M_{\gamma\alpha}^i B_i^{i'} B_{\alpha'}^\gamma = M_{\alpha'\gamma'}^{i'} B_\alpha^{\alpha'} + B_i^{i'} B_{\alpha'\beta}^\gamma x_\gamma^i B_\alpha^{\beta'}.$$

From (1.30), (1.31) and (1.2) it follows (1.28) and (1.29). \square

From Theorem 1.4 it follows

$$(1.32) \quad N_{\beta i}^k = N_{\beta i}^k(x^j, t^\alpha, x_\alpha^j) \quad M_{\beta i}^k = M_{\beta i}^k(x^j, t^\alpha, x_\alpha^j).$$

Theorem 1.5. *The functions $N_{j\beta}^k$ and $N_{\beta j}^k$, further $M_{\alpha\beta}^k$ and $M_{\beta\alpha}^k$ have the same law of transformation.*

Proof. It follows from comparison of (1.19) with (1.28) further (1.20) with (1.29).

Theorem 1.6. *If the natural bases \bar{B}^* and \bar{B} are dual to each other, then the adapted bases B^* and B are dual to each other if and only if*

$$(1.33) \quad N_{j\beta}^k = N_{\beta j}^k \quad M_{\alpha\beta}^k = M_{\beta\alpha}^k.$$

Proof.

$$\begin{aligned} \langle \delta x^i, \delta_j \rangle &= \langle dx^i, \partial_j - N_{j\beta}^k \partial_k^\beta \rangle = \delta_j^i \\ \langle \delta x^i, \delta_\alpha \rangle &= \langle dx^i, \partial_\alpha - M_{\alpha\beta}^k \partial_k^\beta \rangle = 0 \\ \langle \delta x^i, \delta_i^\alpha \rangle &= \langle dx^i, \partial_i^\alpha \rangle = 0 \\ \langle \delta t^\alpha, \delta_i \rangle &= \langle dt^\alpha, \partial_i - N_{i\beta}^k \partial_k^\beta \rangle = 0 \\ \langle \delta t^\alpha, \delta_\beta \rangle &= \langle dt^\alpha, \partial_\beta - M_{\beta\gamma}^k \partial_k^\gamma \rangle = \delta_\beta^\alpha \\ \langle \delta t^\alpha, \delta_i^\beta \rangle &= \langle dt^\alpha, \partial_i^\beta \rangle = 0 \\ \langle \delta x_\alpha^i, \delta_j \rangle &= \langle dx_\alpha^i + M_{\alpha\beta}^i dt^\beta + N_{\alpha k}^i dx^k, \partial_j - N_{j\beta}^k \partial_k^\beta \rangle = \\ &= -N_{j\beta}^k \delta_k^i \delta_\alpha^\beta + N_{\alpha k}^i \delta_j^k = 0 \Rightarrow N_{j\alpha}^i = N_{\alpha j}^i \\ \langle \delta x_\alpha^i, \delta_\beta \rangle &= \langle dx_\alpha^i + M_{\alpha\gamma}^i dt^\gamma + N_{\alpha k}^i dx^k, \partial_\beta - M_{\beta\gamma}^k \partial_k^\gamma \rangle = \\ &= -M_{\beta\gamma}^k \delta_k^i \delta_\alpha^\gamma + M_{\alpha\gamma}^i \delta_\beta^\gamma = 0 \Rightarrow M_{\beta\alpha}^i = M_{\alpha\beta}^i. \square \end{aligned}$$

2. Different kinds of connections on $T(E)$

Let us denote by T_0, T_1, T_2 the subspaces of $T(E)$ generated by $\{\delta_i\}, \{\delta_\alpha\}, \{\delta_i^\alpha\}$ respectively and by T_0^*, T_1^*, T_2^* the subspaces of $T^*(E)$ generated by $\{\delta x^i\}, \{\delta t^\alpha\}$ and $\{\delta x_\alpha^i\}$ respectively.

Some tensor T on $T_0^* \otimes T_0 \otimes T_1^* \otimes T_1 \otimes T_2^* \otimes T_2$ is given by

$$T = T_{i\alpha}^{j\beta\delta h}{}_{k\gamma} \delta x^i \otimes \delta_j \otimes \delta t^\alpha \otimes \delta_\beta \otimes \delta x_\delta^k \otimes \delta_h^\gamma.$$

If in another chart $(U', \varphi')T$ has the form

$$T = T_{i'\alpha'}^{j'\beta'\delta' h'} \delta x^{i'} \otimes \delta_{j'} \otimes \delta t^{\alpha'} \otimes \delta_{\beta'} \otimes \delta x_{\delta'}^{k'} \otimes \delta_{h'}^{\gamma'},$$

then using the transformation law of adapted bases vectors, which span $T_0, T_1, T_2, T_1^*, T_1^*, T_2^*$ ((1.18) and (1.27)) we get

$$(2.1) \quad T_{i\alpha}^{j\beta\delta h}{}_{k\gamma} = T_{i'\alpha'}^{j'\beta'\delta' h'} B_{ij'}^{j\beta\delta h}{}_{k\gamma} B_{i'\alpha'}^{i\beta\delta h}{}_{k\gamma},$$

where

$$B_{ij'}^{j\beta\delta h}{}_{k\gamma} = B_i^{i'} B_{j'}^j B_{\alpha'}^{\alpha} B_{\beta'}^{\beta} B_{\delta'}^{\delta} B_k^{k'} B_{h'}^h B_{\gamma'}^{\gamma}.$$

Let us suppose that on $T^*(E) \otimes T^*(E)$ the metric tensor G is given in normal form:

$$(2.2) \quad G = g_{ij} \delta x^i \otimes \delta x^j + g_{\alpha\beta} \delta t^\alpha \otimes \delta t^\beta + g_{ij}^{\alpha\beta} \delta x_\alpha^i \delta x_\beta^j.$$

In this case T_0, T_1 and T_2 are mutually orthogonal with respect to G .

Theorem 2.1. *The following equations are coordinate invariant*

$$(2.3) \quad \begin{aligned} g_{ij} \delta x^i &= \delta_j \Leftrightarrow g^{ij} \delta_j = \delta x^i \\ g_{\alpha\beta} \delta t^\alpha &= \delta_\beta \Leftrightarrow g^{\alpha\beta} \delta_\beta = \delta t^\alpha \\ g_{ij}^{\alpha\beta} \delta x_\alpha^i &= \delta_j^\beta \Leftrightarrow g_{\alpha\beta}^{ij} \delta_j^\beta = \delta x_\alpha^i \end{aligned}$$

where

$$(2.4) \quad g_{ij} g^{jk} = \delta_i^k, \quad g_{\alpha\beta} g^{\beta\gamma} = \delta_\alpha^\gamma, \quad g_{ij}^{\alpha\beta} g_{\beta\delta}^{jk} = \delta_i^k \delta_\delta^\alpha.$$

Proof. Using (1.18), (1.27) and (2.1) we have

$$g_{i'j'} \delta x^{i'} = B_{i'j'}^{i\beta\delta h}{}_{k\gamma} g_{ij} \delta x^i = g_{kj} B_{j'}^j \delta x^k = B_{j'}^j \delta_j = \delta_{j'},$$

$$g_{\alpha'\beta'} \delta t^{\alpha'} = B_{\alpha'\beta'}^{\alpha\beta} g_{\alpha\beta} B_{\gamma'}^{\beta\delta} \delta t^\gamma = g_{\alpha\gamma} B_{\alpha'}^\alpha \delta t^\gamma = B_{\alpha'}^\alpha \delta_\alpha = \delta_{\alpha'},$$

$$g_{i'j'}^{\alpha'\beta'} \delta x_{\alpha'}^{i'} = g_{ij}^{\alpha\beta} B_{\alpha'\beta'}^{\alpha\beta} B_{i'j'}^{i\beta\delta h}{}_{k\gamma} \delta x_\delta^k = g_{kj}^{\delta\beta} B_{\beta'j'}^{\beta\delta} \delta x_\delta^k = B_{\beta'j'}^{\beta\delta} \delta_j^\beta = \delta_{j'}^{\beta'}.$$

If the relations (2.3) are valid, using the metric tensor, we can change the place of indices in tensors in the following way:

$$(2.5) \quad T_i^j \delta x^i \otimes \delta_j = T_i^j g^{ik} \delta_k \otimes \delta_j = T^{kj} \delta_k \otimes \delta_j,$$

$$T_i^j \delta x^i \otimes \delta_j = T_i^j \delta x^i \otimes g_{kj} \delta x^k = T_{ik} \delta x^i \otimes \delta x^k,$$

$$T_i^{\alpha j} \delta x_\alpha^i \otimes \delta_j^\beta = T_i^{\alpha j} g_{\alpha\epsilon}^i{}^k \delta_k^\epsilon \otimes \delta_j^\beta = T_{\epsilon\beta}^{kj} \delta_k^\epsilon \otimes \delta_j^\beta, \dots$$

Theorem 2.2. *In tensors the indices can change their place using the metric tensor only, when*

$$(2.6) \quad \begin{aligned} g_{ij} &= g_{ij}(x^k, t^\gamma, x_\delta^h), \\ g_{\alpha\beta} &= g_{\alpha\beta}(x^k, t^\gamma, x_\gamma^h), \\ g_{ij}^{\alpha\beta} &= g_{ij}^{\alpha\beta}(x^k, t^\gamma, x_\delta^h). \end{aligned}$$

Proof. As δ_i is the function of $N_{i\beta}^k$, δ_β of $M_{\beta\gamma}^k$ and δx_α^i is the function of $N_{i\beta}^k$ and $M_{\beta\gamma}^k$ and (1.32) is valid, from (2.4) we conclude (2.6).

Definition 2.1. *The linear connection $\nabla : (T(E) \times T(E) \rightarrow T(E)$, $\nabla : (X, Y) \rightarrow \nabla_X Y$ for $\forall X, Y \in T(E)$ is defined by*

$$(2.7) \quad \begin{aligned} \nabla_{\delta_i} \delta_j &= \underline{\Gamma_{j\ i}^k} \delta_k + \Gamma_{j\ i}^\gamma \delta_\gamma + \Gamma_{j\gamma i}^k \delta_k^\gamma, \\ \nabla_{\delta_i} \delta_\alpha &= \Gamma_{\alpha\ i}^k \delta_k + \underline{\Gamma_{\alpha\ i}^\gamma} \delta_\gamma + \Gamma_{\alpha\gamma i}^k \delta_k^\gamma, \\ \nabla_{\delta_i} \delta_j^\beta &= \Gamma_{j\ i}^{\beta k} \delta_k + \Gamma_{j\ i}^{\beta\gamma} \delta_\gamma + \underline{\Gamma_{j\gamma i}^{\beta k}} \delta_k^\gamma, \\ \nabla_{\delta_\alpha} \delta_j &= \underline{\Gamma_{j\ \alpha}^k} \delta_k + \Gamma_{j\ \alpha}^\gamma \delta_\gamma + \Gamma_{j\ \gamma\alpha}^k \delta_k^\gamma, \\ \nabla_{\delta_\alpha} \delta_\beta &= \Gamma_{\beta\ \alpha}^k \delta_k + \underline{\Gamma_{\beta\ \alpha}^\gamma} \delta_\gamma + \Gamma_{\beta\gamma\alpha}^k \delta_k^\gamma, \\ \nabla_{\delta_\alpha} \delta_j^\beta &= \Gamma_{j\ \alpha}^{\beta k} \delta_k + \Gamma_{j\ \alpha}^{\beta\gamma} \delta_\gamma + \underline{\Gamma_{j\gamma\alpha}^{\beta k}} \delta_k^\gamma, \\ \nabla_{\delta_i^\alpha} \delta_j &= \underline{\Gamma_{j\ i}^{k\alpha}} \delta_k + \Gamma_{j\ i}^{\gamma\alpha} \delta_\gamma + \Gamma_{j\gamma i}^{k\alpha} \delta_k^\gamma, \\ \nabla_{\delta_i^\alpha} \delta_\beta &= \Gamma_{\beta\ i}^{k\alpha} \delta_k + \underline{\Gamma_{\beta\ i}^{\gamma\alpha}} \delta_\gamma + \Gamma_{\beta\gamma i}^{k\alpha} \delta_k^\gamma, \\ \nabla_{\delta_i^\alpha} \delta_j^\beta &= \Gamma_{j\ i}^{\beta k\alpha} \delta_k + \Gamma_{j\ i}^{\beta\gamma\alpha} \delta_\gamma + \underline{\Gamma_{j\gamma i}^{\beta k\alpha}} \delta_k^\gamma. \end{aligned}$$

Definition 2.2. *The linear connection defined by (2.7) is d -connection if on the right hand side in (2.7) only the underlined terms remain, the other are equal to zero.*

It can be seen, that for the d -connection if Y belongs to one of T_0 , T_1 or T_2 , then $\nabla_X Y$ belongs to the same subspace of $T(E)$ for every $X \in T(E)$.

Remark. In papers [6], [7], [8], [9] d -connection is considered.

Definition 2.3. *The linear connection is called strongly distinguished connection (s.d. connection) if it is defined by*

$$(2.8) \quad \nabla_{\delta_i} \delta_j = \Gamma_{j\ i}^k \delta_k, \nabla_{\delta_\alpha} \delta_\beta = \Gamma_{\beta\ \alpha}^\gamma \delta_\gamma, \nabla_{\delta_i^\alpha} \delta_j^\beta = \Gamma_{j\gamma i}^{\beta k\alpha} \delta_k^\gamma,$$

the other connection coefficients are equal to zero.

For the s.d. connection X, Y and $\nabla_X Y$ belong to the same subspace T_0 or T_1 or T_2 .

Proposition 2.1. *The components of the linear connection ∇ under transformations given by (1.1) behave as follows:*

$$(2.9) \quad (a) \quad \Gamma_{j' i'}^{k'} = \Gamma_{j i}^k B_{i' j' k}^{i j k'} + B_{j' i'}^k B_k^{k'}$$

$$(b) \quad \Gamma_{j' i'}^{\alpha'} = \Gamma_{j i}^\alpha B_{i' j' \alpha}^{i j \alpha'}$$

$$(c) \quad \Gamma_{j' \beta' i'}^{k'} = \Gamma_{j \beta i}^k B_{j' k \beta' i'}^{j k \beta i}$$

$$(2.10) \quad (a) \quad \Gamma_{\alpha' i'}^{k'} = \Gamma_{\alpha i}^k B_{\alpha' k i'}^{\alpha k' i}$$

$$(b) \quad \Gamma_{\alpha' i'}^{\beta'} = \Gamma_{\alpha i}^\beta B_{\alpha' \beta i'}^{\alpha \beta' i}$$

$$(c) \quad \Gamma_{\alpha' \beta' i'}^{k'} = \Gamma_{\alpha \beta i}^k B_{\alpha' k \beta' i'}^{\alpha k' \beta i}$$

$$(2.11) \quad (a) \quad \Gamma_{j' i'}^{\beta' k'} = \Gamma_{j i}^{\beta k} B_{j' \beta k i'}^{j \beta' k' i}$$

$$(b) \quad \Gamma_{j' i'}^{\beta' \gamma'} = \Gamma_{j i}^{\beta \gamma} B_{j' \beta \gamma i'}^{j \beta' \gamma' i}$$

$$(c) \quad \Gamma_{j' \gamma' i'}^{\beta' k'} = \Gamma_{j \gamma i}^{\beta k} B_{j' \beta k \gamma' i'}^{j \beta' k' \gamma i} + \delta_{\gamma'}^{\beta'} B_{j' i'}^k B_k^{k'}$$

$$(2.12) \quad (a) \quad \Gamma_{j' \alpha'}^{k'} = \Gamma_{j \alpha}^k B_{j' k \alpha'}^{j k' \alpha}$$

$$(b) \quad \Gamma_{j' \alpha'}^{\gamma'} = \Gamma_{j \alpha}^\gamma B_{j' \gamma \alpha'}^{j \gamma' \alpha}$$

$$(c) \quad \Gamma_{j' \gamma' \alpha'}^{k'} = \Gamma_{j \gamma \alpha}^k B_{j' k \gamma' \alpha'}^{j k' \gamma \alpha}$$

$$(2.13) \quad (a) \quad \Gamma_{\beta' \alpha'}^{k'} = \Gamma_{\beta \alpha}^k B_{\beta' k \alpha'}^{\beta k' \alpha}$$

$$(b) \quad \Gamma_{\beta' \alpha'}^{\gamma'} = \Gamma_{\beta \alpha}^\gamma B_{\beta' \gamma \alpha'}^{\beta \gamma' \alpha} + B_{\beta' \alpha'}^\gamma B_\gamma^{\gamma'}$$

$$(c) \quad \Gamma_{\beta' \gamma' \alpha'}^{k'} = \Gamma_{\beta \gamma \alpha}^k B_{\beta' k \gamma' \alpha'}^{\beta k' \gamma \alpha}$$

$$(2.14) \quad (a) \quad \Gamma_{j' \alpha'}^{\beta' k'} = \Gamma_{j \alpha}^{\beta k} B_{j' \beta k \alpha'}^{j \beta' k' \alpha}$$

$$(b) \quad \Gamma_{j' \alpha'}^{\beta' \gamma'} = \Gamma_{j \alpha}^{\beta \gamma} B_{j' \beta \gamma \alpha'}^{j \beta' \gamma' \alpha}$$

$$(c) \quad \Gamma_{j' \gamma' \alpha'}^{\beta' k'} = \Gamma_{j \gamma \alpha}^{\beta k} B_{j' \beta k \gamma' \alpha'}^{\beta i \beta' k' \gamma \alpha} + \delta_{j'}^{k'} B_{\alpha \gamma}^{\beta'} B_{\alpha'}^\alpha B_{\gamma'}^\gamma$$

$$(2.15) \quad \begin{aligned} (a) \quad & \Gamma_{j' i'}^{k' \alpha'} = \Gamma_{j i}^{k \alpha} B_{j' k \alpha i'}^{j k' \alpha' i} \\ (b) \quad & \Gamma_{j' i'}^{\gamma' \alpha'} = \Gamma_{j i}^{\gamma \alpha} B_{j' \gamma \alpha i'}^{j \gamma' \alpha' i} \\ (c) \quad & \Gamma_{j' \gamma' i'}^{k' \alpha'} = \Gamma_{j \gamma i}^{k \alpha} B_{j' k \gamma' \alpha i'}^{j k' \gamma \alpha' i} \end{aligned}$$

$$(2.16) \quad \begin{aligned} (a) \quad & \Gamma_{\beta' i'}^{k' \alpha'} = \Gamma_{\beta i}^{k \alpha} B_{\beta' k \alpha i'}^{\beta k' \alpha' i} \\ (b) \quad & \Gamma_{\beta' i'}^{\gamma' \alpha'} = \Gamma_{\beta i}^{\gamma \alpha} B_{\beta' \gamma \alpha i'}^{\beta \gamma' \alpha' i} \\ (c) \quad & \Gamma_{\beta' \gamma' i'}^{k' \alpha'} = \Gamma_{\beta \gamma i}^{k \alpha} B_{\beta' k \gamma' \alpha i'}^{\beta k' \gamma \alpha' i} \end{aligned}$$

$$(2.17) \quad \begin{aligned} (a) \quad & \Gamma_{j' i'}^{\beta' k' \alpha'} = \Gamma_{j i}^{\beta \gamma \alpha} B_{j' \beta k \alpha i'}^{j \beta' k' \alpha' i} \\ (b) \quad & \Gamma_{j' i'}^{\beta' \gamma' \alpha'} = \Gamma_{j i}^{\beta \gamma \alpha} B_{j' \beta \gamma \alpha i'}^{j \beta' \gamma' \alpha' i} \\ (c) \quad & \Gamma_{j' \gamma' i'}^{\beta' k' \alpha'} = \Gamma_{j \gamma i}^{\beta k \alpha} B_{j' \beta k \gamma' \alpha i'}^{j \beta' k' \gamma \alpha' i} \end{aligned}$$

Proof. From

$$\nabla_{\delta_{i'}} \delta_{j'} = \nabla_{B_{i'}^i \delta_i} B_{j'}^j \delta_j = B_{i'}^i (\delta_i B_{j'}^j) \delta_j + B_{i' j'}^{i j} \nabla_{\delta_i} \delta_j,$$

$$\nabla_{\delta_{i'}} \delta_{j'} = \Gamma_{j' i'}^{k' \alpha'} \delta_{k'} + \Gamma_{j' i'}^{\alpha'} \delta_{\alpha'} + \Gamma_{j' \beta' i'}^{k' \alpha'} \delta_{k'}^{\beta'},$$

(1.17) and (2.7) we obtain (2.9a), (2.9b) and (2.9c). The other relations can be obtained on the similar way.

From the above we have

Theorem 2.3. *All coefficients of linear connection ∇ defined by (2.7) are transforming as tensors except $\Gamma_{j i}^k$, $\Gamma_{\beta \alpha}^\gamma$, $\Gamma_{j \gamma \alpha}^{\beta j}$, $\Gamma_{j \beta i}^{\beta k}$ (no summation over j and β).*

They have the following law of transformation:

$$(2.18) \quad \Gamma_{j' i'}^{k'} = \Gamma_{j i}^k B_{i' j' k}^{i j k'} + B_{j' i'}^k B_k^{k'}$$

$$(2.19) \quad \Gamma_{\beta' \alpha'}^{\gamma'} = \Gamma_{\beta \alpha}^\gamma B_{\beta' \gamma \alpha'}^{\beta \gamma' \alpha} + B_{\beta' \alpha'}^\gamma B_\gamma^{\gamma'}$$

$$(2.20) \quad \Gamma_{j' \beta' i'}^{\beta' k'} = \Gamma_{j \gamma i}^{\beta k} B_{j' \beta k \beta' i'}^{j \beta' k' \gamma i} + B_{j' i'}^k B_k^{k'}$$

$$(2.21) \quad \Gamma_{j' \gamma' \alpha'}^{\beta' j'} = \Gamma_{j \gamma \alpha}^{\beta k} B_{j' \beta k \gamma' \alpha'}^{j \beta' j' \gamma \alpha} + B_{\alpha' \gamma}^{\beta'} B_{\alpha'}^\alpha B_{\gamma'}^\gamma$$

(j' and β' are fixed).

Definition 2.4. *The action of the linear connection ∇ on the $T^*(E)$, $\nabla : T(E) \times T^*(E) \rightarrow T^*(E)$, $\nabla : (X, \omega) \rightarrow \nabla_X \omega \in T^*(E)$, $X \in T(E)$, $\omega \in T^*(E)$ is defined by*

$$\begin{aligned}
(2.22) \quad \nabla_{\delta_i} \delta x^j &= \bar{\Gamma}_{ki}^j \delta x^k + \bar{\Gamma}_{\gamma i}^j \delta t^\gamma + \bar{\Gamma}_{ki}^{j\gamma} \delta x_\gamma^k \\
\nabla_{\delta_i} \delta t^\beta &= \bar{\Gamma}_{ki}^\beta \delta x^k + \bar{\Gamma}_{\gamma i}^\beta \delta t^\gamma + \bar{\Gamma}_{ki}^{\beta\gamma} \delta x_\gamma^k \\
\nabla_{\delta_i} \delta x_\delta^h &= \bar{\Gamma}_{\delta ki}^h \delta x^k + \bar{\Gamma}_{\delta \gamma i}^h \delta t^\gamma + \bar{\Gamma}_{\delta ki}^{h\gamma} \delta x_\gamma^k \\
\nabla_{\delta_\alpha} \delta x^j &= \bar{\Gamma}_{k\alpha}^j \delta x^k + \bar{\Gamma}_{\gamma\alpha}^j \delta t^\gamma + \bar{\Gamma}_{k\alpha}^{j\gamma} \delta x_\gamma^k \\
\nabla_{\delta_\alpha} \delta t^\beta &= \bar{\Gamma}_{k\alpha}^\beta \delta x^k + \bar{\Gamma}_{\gamma\alpha}^\beta \delta t^\gamma + \bar{\Gamma}_{k\alpha}^{\beta\gamma} \delta x_\gamma^k \\
\nabla_{\delta_\alpha} \delta x_\delta^h &= \bar{\Gamma}_{\delta k\alpha}^h \delta x^k + \bar{\Gamma}_{\delta \gamma\alpha}^h \delta t^\gamma + \bar{\Gamma}_{\delta k\alpha}^{h\gamma} \delta x_\gamma^k \\
\nabla_{\delta_i^\alpha} \delta x^j &= \bar{\Gamma}_{ki}^{j\alpha} \delta x^k + \bar{\Gamma}_{\gamma i}^{j\alpha} \delta t^\gamma + \bar{\Gamma}_{ki}^{j\gamma\alpha} \delta x_\gamma^k \\
\nabla_{\delta_i^\alpha} \delta t^\beta &= \bar{\Gamma}_{ki}^{\beta\alpha} \delta x^k + \bar{\Gamma}_{\gamma i}^{\beta\alpha} \delta t^\gamma + \bar{\Gamma}_{ki}^{\beta\gamma\alpha} \delta x_\gamma^k \\
\nabla_{\delta_i^\alpha} \delta x_\beta^j &= \bar{\Gamma}_{\beta ki}^{j\alpha} \delta x^k + \bar{\Gamma}_{\beta \gamma i}^{j\alpha} \delta t^\gamma + \bar{\Gamma}_{\beta ki}^{j\gamma\alpha} \delta x_\gamma^k.
\end{aligned}$$

Theorem 2.4. *The connection coefficients Γ and $\bar{\Gamma}$ are connected by:*

$$\begin{aligned}
(2.23) \quad \bar{\Gamma}_{ki}^j &= -\Gamma_{k i}^j, \quad \bar{\Gamma}_{\gamma i}^j = -\Gamma_{\gamma i}^j, \quad \bar{\Gamma}_{ki}^{j\gamma} = -\Gamma_{k i}^{\gamma j} \\
\bar{\Gamma}_{ki}^{\beta\gamma} &= -\Gamma_{k i}^{\gamma\beta}, \quad \bar{\Gamma}_{\gamma i}^{\beta\gamma} = -\Gamma_{\gamma i}^{\beta\gamma}, \quad \bar{\Gamma}_{ki}^{\beta\gamma\alpha} = -\Gamma_{k i}^{\alpha\gamma\beta} \\
\bar{\Gamma}_{\delta ki}^h &= -\Gamma_{k \delta i}^h, \quad \bar{\Gamma}_{\delta \gamma i}^h = -\Gamma_{\gamma \delta i}^h, \quad \bar{\Gamma}_{\delta k i}^{h\gamma} = -\Gamma_{k \delta i}^{\gamma h}.
\end{aligned}$$

All formulae in (2.23) are valid if everywhere the index i is substituted by α or by i^α .

Proof. From the duality of the adapted bases B and B^* we obtain

$$\begin{aligned}
\langle \delta x^h, \delta_j \rangle &= \delta_j^h, \quad \langle \delta x^h, \delta_\beta \rangle = 0, \quad \langle \delta x^h, \delta_k^\gamma \rangle = 0 \Rightarrow \\
\langle \nabla_{\delta_i} \delta x^h, \delta_j \rangle &= \langle \bar{\Gamma}_{ki}^h \delta x^k + \bar{\Gamma}_{\gamma i}^h \delta t^\gamma + \bar{\Gamma}_{ki}^{h\gamma} \delta x_\gamma^k, \delta_j \rangle = \\
-\langle \delta x^h, \nabla_{\delta_i} \delta_j \rangle &= -\langle \delta x^h, \Gamma_{j i}^k \delta_h + \Gamma_{j i}^\beta \delta_\beta + \Gamma_{j \gamma i}^k \delta_k^\gamma \rangle \Rightarrow \\
(2.24) \quad \bar{\Gamma}_{ji}^h &= -\Gamma_{j i}^h
\end{aligned}$$

$$\begin{aligned}
\langle \nabla_{\delta_i} \delta x^h, \delta_\beta \rangle &= \langle \bar{\Gamma}_{ki}^h \delta x^k + \bar{\Gamma}_{\gamma i}^h \delta t^\gamma + \bar{\Gamma}_{ki}^{h\gamma} \delta x_\gamma^k, \delta_\beta \rangle = \\
-\langle \delta x^h, \nabla_{\delta_i} \delta_\beta \rangle &= -\langle \delta x^h, \Gamma_{\beta i}^k \delta_k + \Gamma_{\beta i}^\gamma \delta_\gamma + \Gamma_{\beta \gamma i}^k \delta_k^\gamma \rangle \Rightarrow \\
(2.25) \quad \bar{\Gamma}_{\beta i}^h &= -\Gamma_{\beta i}^h.
\end{aligned}$$

$$\begin{aligned}
\langle \nabla_{\delta_i} \delta x^h, \delta_k^\gamma \rangle &= \langle \bar{\Gamma}_{ki}^h \delta x^k + \bar{\Gamma}_{\gamma i}^h \delta t^\gamma + \bar{\Gamma}_{j i}^{h\delta} \delta x_\delta^j, \delta_k^\gamma \rangle = \\
-\langle \delta x^h, \nabla_{\delta_i} \delta_k^\gamma \rangle &= -\langle \delta x^h, \Gamma_{k i}^{\gamma j} \delta_j + \Gamma_{k i}^{\gamma \beta} \delta_\beta + \Gamma_{k \delta i}^{\gamma h} \delta_\delta^h \rangle \Rightarrow \\
(2.26) \quad \bar{\Gamma}_{ki}^{h\gamma} &= -\Gamma_{k i}^{\gamma h}.
\end{aligned}$$

(2.24), (2.25) and (2.26) are the first three equations in (2.23). The other can be proved on the similar way. \square

Theorem 2.5. *If the linear connection ∇ acts on $T(E)$ as d -connection, then its action on $T^*(E)$ is given by*

$$\begin{aligned}
(2.27) \quad \nabla_{\delta_i} \delta x^j &= -\Gamma_{k i}^j \delta x^k, \quad \nabla_{\delta_i} \delta t^\alpha = -\Gamma_{\gamma i}^\alpha \delta t^\gamma, \quad \nabla_{\delta_i} \delta x_\delta^h = -\Gamma_{k \delta i}^{\gamma h} \delta x_\gamma^k \\
\nabla_{\delta_\alpha} \delta x^j &= -\Gamma_{k \alpha}^j \delta x^k, \quad \nabla_{\delta_\alpha} \delta t^\beta = -\Gamma_{\gamma \alpha}^\beta \delta t^\gamma, \quad \nabla_{\delta_\alpha} \delta x_\delta^h = -\Gamma_{k \delta \alpha}^{\gamma h} \delta x_\gamma^k \\
\nabla_{\delta_i^\alpha} \delta x^j &= -\Gamma_{k i}^j \delta x^k, \quad \nabla_{\delta_i^\alpha} \delta t^\beta = -\Gamma_{\gamma i}^{\beta \alpha} \delta t^\gamma, \quad \nabla_{\delta_i^\alpha} \delta x_\delta^h = -\Gamma_{k \delta i}^{\gamma h \alpha} \delta x_\gamma^k.
\end{aligned}$$

Theorem 2.6. *If the linear connection ∇ on $T(E)$ as s.d. connection, then its action on $T^*(E)$ is given by*

$$\begin{aligned}
(2.28) \quad \nabla_{\delta_i} \delta x^j &= -\Gamma_{k i}^j \delta x^k, \\
\nabla_{\delta_\alpha} \delta t^\beta &= -\Gamma_{\gamma \alpha}^\beta \delta t^\gamma, \\
\nabla_{\delta_i^\alpha} \delta x_\beta^j &= -\Gamma_{k \beta i}^{\gamma j \alpha} \delta x_\gamma^k,
\end{aligned}$$

the other connection coefficients are equal to zero.

Theorem 2.7. *If $X, Y \in T(E)$, i.e.*

$$\begin{aligned}
X &= X^A \delta_A = X^i \delta_i + X^\alpha \delta_\alpha + X_\alpha^i \delta_i^\alpha \\
Y &= Y^B \delta_B = Y^j \delta_j + Y^\beta \delta_\beta + Y_\beta^j \delta_j^\beta,
\end{aligned}$$

then

$$\begin{aligned}
(2.29) \quad \nabla_Y X &= X|_B^A Y^B \delta_A = \\
&X^i|_j Y^j \delta_i + X^\alpha|_j Y^j \delta_\alpha + X_\alpha^i|_j Y^j \delta_i^\alpha + \\
&X^i|_\beta Y^\beta \delta_i + X^\alpha|_\beta Y^\beta \delta_\alpha + X_\alpha^i|_\beta Y^\beta \delta_i^\alpha + \\
&X^i|_j^\beta Y_\beta^j \delta_i + X^\alpha|_j^\beta Y_\beta^j \delta_\alpha + X_\alpha^i|_j^\beta Y_\beta^j \delta_i^\alpha,
\end{aligned}$$

where

$$\begin{aligned}
(2.30) \quad X|_u^v &= \delta_u X^v + \Gamma_{k u}^v X^k + \Gamma_{\gamma u}^v X^\gamma + \Gamma_{k u}^{\gamma v} X_\gamma^k, \\
u &\in \{j, \beta, \beta_j\}, \quad v \in \{i, \alpha, i_\alpha\}.
\end{aligned}$$

For instance we have

$$\begin{aligned} X^i|_j &= \delta_j X^i + \Gamma_{k j}^i X^k + \Gamma_{\gamma j}^i X^\gamma + \Gamma_{k j}^{\gamma i} X^\gamma, \\ X_\alpha^i|_j^\beta &= \delta_j^\beta X_\alpha^i + \Gamma_{k\alpha j}^{i\beta} X^k + \Gamma_{\gamma\alpha j}^{i\beta} X^\gamma + \Gamma_{k\alpha j}^{\gamma i\beta} X^\gamma, \dots \end{aligned}$$

Theorem 2.8. *If $\omega \in T^*(E)$, i.e.*

$$\omega = \omega_i \delta x^i + \omega_\alpha \delta t^\alpha + \omega_i^\alpha \delta x_\alpha^i,$$

then

$$\begin{aligned} (2.31) \quad \nabla_Y \omega &= \omega_{i|j} Y^j \delta x^i + \omega_{\alpha|j} Y^j \delta t^\alpha + \omega_{i|j}^\alpha Y^j \delta x_\alpha^i + \\ &\quad \omega_{i|\beta} Y^\beta \delta x^i + \omega_{\alpha|\beta} Y^\beta \delta t^\alpha + \omega_{i|\beta}^\alpha Y^\beta \delta x_\alpha^i + \\ &\quad \omega_i|_j^\beta Y_\beta^j \delta x^i + \omega_\alpha|_j^\beta Y_\beta^j \delta t^\alpha + \omega_i^\alpha|_j^\beta Y_\beta^j \delta x_\alpha^i, \end{aligned}$$

where

$$\begin{aligned} (2.32) \quad \omega_{v|u} &= \delta_u \omega_v - \Gamma_{v u}^k \omega_k - \Gamma_{v u}^\gamma \omega_\gamma - \Gamma_{v \gamma u}^k \omega_k^\gamma \\ u &\in \{j, \beta, \beta_j\}, \quad v \in \{i, \alpha, \alpha_i\}. \end{aligned}$$

For instance

$$\begin{aligned} \omega_{i|\beta}^\alpha &= \delta_\beta \omega_\alpha^i - \Gamma_{i \beta}^{\alpha k} \omega_k - \Gamma_{i \beta}^{\alpha \gamma} \omega_\gamma - \Gamma_{i \gamma \beta}^{\alpha k} \omega_k^\gamma, \\ \omega_i^\alpha|_j^\beta &= \delta_j^\beta \omega_i^\alpha - \Gamma_{i j}^{\alpha k \beta} \omega_k - \Gamma_{i j}^{\alpha \gamma \beta} \omega_\gamma - \Gamma_{i \gamma j}^{\alpha k \beta} \omega_k^\gamma, \dots \end{aligned}$$

If the function $f = f(x^k, t^\gamma, x_\gamma^k)$ is defined on E , then

$$(2.33) \quad \nabla_Y f = f_{|j} Y^j + f_{|\beta} Y^\beta + f_{|j}^\beta Y_\beta^j,$$

where

$$\begin{aligned} (2.34) \quad f_{|j} &= \delta_j f = (\partial_j - N_{\gamma j}^k \partial_k^\gamma) f \\ f_{|\beta} &= \delta_\beta f = (\partial_\beta - M_{\gamma \beta}^k \partial_k^\gamma) f \\ f_{|j}^\beta &= \partial_j^\beta f. \end{aligned}$$

Theorem 2.9. *For the d-connection (2.29) is valid, but now we have*

$$\begin{aligned} (2.35) \quad X^i|_u &= \delta_u X^i + \Gamma_{j u}^i X^j \\ X_\alpha^i|_u &= \delta_u X_\alpha^i + \Gamma_{\beta u}^{\alpha i} X^\beta \\ X_\alpha^i|_u &= \delta_u X_\alpha^i + \Gamma_{k\alpha u}^{\gamma i} X^\gamma \\ u &\in \{j, \beta, \beta_j\} \end{aligned}$$

For the s.d. connection we have

$$(2.36) \quad \nabla_X Y = X^i|_j Y^j \delta_i + X^\alpha|_\beta Y^\beta \delta_\alpha + X^\alpha|_j^\beta Y_\beta^j \delta_i^\alpha,$$

and

$$(2.37) \quad \begin{aligned} X^i|_j &= \delta_j X^i + \Gamma_{k j}^i X^k, \\ X^\alpha|_\beta &= \delta_\beta X^\alpha + \Gamma_{\gamma \beta}^\alpha X^\gamma, \\ X^\alpha|_j^\beta &= \delta_j^\beta X^\alpha + \Gamma_{k \alpha j}^{\gamma \beta} X^\gamma. \end{aligned}$$

Definition 2.5. *The s.d. connection is called recurrent connection if for the metric tensor*

$$g = g_{ij} \delta x^i \otimes \delta x^j + g_{\alpha\beta} \delta t^\alpha \otimes \delta t^\beta + g_{ij}^{\alpha\beta} \delta x_\alpha^i \otimes \delta x_\beta^j$$

the following relations are valid:

$$(2.38) \quad \begin{aligned} g_{ij|k} &= \delta_k g_{ij} - g_{hj} \Gamma_{i k}^h - g_{ih} \Gamma_{j k}^h = \lambda_k g_{ij} \\ g_{\alpha\beta|\gamma} &= \delta_\gamma g_{\alpha\beta} - g_{\delta\beta} \Gamma_{\alpha \gamma}^\delta - g_{\alpha\delta} \Gamma_{\beta \gamma}^\delta = \lambda_\gamma g_{\alpha\beta} \\ g_{ij}^{\alpha\beta}|_k &= \delta_k^\gamma g_{ij}^{\alpha\beta} - g_{hj}^{\delta\beta} \Gamma_{i \delta k}^{\alpha h \gamma} - g_{ih}^{\alpha\delta} \Gamma_{j \delta k}^{\beta h \gamma} = \lambda_k^\gamma g_{ij}^{\alpha\beta}, \end{aligned}$$

where

$$(2.39) \quad \lambda = \lambda_k \delta x^k + \lambda_\gamma \delta t^\gamma + \lambda_k^\gamma \delta x_\gamma^k$$

is a 1-form field. If in (2.38)

$$\lambda_h = 0, \quad \lambda_\gamma = 0, \quad \lambda_h^\gamma = 0$$

the connection is called metric connection.

Using the usual procedure the connection coefficients can be obtained as functions of the metric tensors and the one form field λ .

3. The torsion tensor

The torsion tensor in the space E is given as usual by

$$T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y].$$

Proposition 3.1. *The Lie brackets on $T(E)$ are given by*

$$(3.1) \quad \begin{aligned} [\delta_i, \delta_j] &= K_{j \delta_i}^h \delta_h^\delta, \\ K_{j \delta_i}^h &= -[(\partial_i N_{\delta j}^h - N_{\gamma i}^k \partial_k^\gamma N_{\delta j}^h) - (i/j)] \\ [\delta_i, \delta_\beta] &= K_{\beta \delta_i}^h \delta_h^\delta, \end{aligned}$$

$$\begin{aligned}
K_{\beta\delta i}^h &= -[(\partial_i M_{\delta\beta}^h - N_{\gamma i}^k \partial_k^\gamma M_{\delta\beta}^h) + \\
&\quad (\partial_\beta N_{\delta i}^h - M_{\gamma\beta}^k \partial_k^\gamma N_{\delta i}^h)] \\
[\delta_i, \delta_j^\beta] &= K_{j\delta i}^{\beta h} \delta_h^\delta, \quad K_{j\delta i}^{\beta h} = \partial_j^\beta N_{\delta i}^k \\
[\delta_\alpha, \delta_\beta] &= K_{\beta\delta\alpha}^h \delta_h^\delta, \\
K_{\beta\delta\alpha}^h &= [(\partial_\alpha M_{\delta\beta}^h - M_{\gamma\alpha}^k \partial_k^\gamma M_{\delta\beta}^h) - (\alpha/\beta)] \\
[\delta_\alpha, \delta_j^\beta] &= K_{j\delta\alpha}^{\beta h} \delta_h^\delta, \quad K_{j\delta\alpha}^{\beta h} = \partial_j^\beta M_{\delta\alpha}^h \\
[\delta_i^\alpha, \delta_j^\beta] &= 0.
\end{aligned}$$

From the above it follows that all Lie brackets of the basis vectors of $T(E)$ lie in T_2 , generated by $\{\delta_h^\delta\}$.

The components of the torsion tensors are:

$$(3.2) \quad T(\delta_i, \delta_j) = T_{j\ i}^h \delta_h + T_{j\ i}^\alpha \delta_\alpha + T_{j\ \delta i}^h \delta_h^\delta,$$

where

$$\begin{aligned}
T_{j\ i}^k &= \Gamma_{j\ i}^k - \Gamma_{i\ j}^k \\
T_{j\ i}^\alpha &= \Gamma_{j\ i}^\alpha - \Gamma_{i\ j}^\alpha \\
T_{j\ \delta i}^h &= \Gamma_{j\ \delta i}^h - \Gamma_{i\ \delta j}^h - K_{j\ \delta i}^h.
\end{aligned}$$

$$(3.3) \quad T(\delta_i, \delta_\alpha) = T_{\alpha\ i}^k + T_{\alpha\ i}^\beta \delta_\beta + T_{\alpha\delta i}^h \delta_h^\delta,$$

where

$$\begin{aligned}
T_{\alpha\ i}^k &= \Gamma_{\alpha\ i}^k - \Gamma_{i\ \alpha}^k \\
T_{\alpha\ i}^\beta &= \Gamma_{\alpha\ i}^\beta - \Gamma_{i\ \alpha}^\beta \\
T_{\alpha\ \delta i}^h &= \Gamma_{\alpha\ \delta i}^h - \Gamma_{i\ \delta\alpha}^h - K_{\alpha\delta i}^h,
\end{aligned}$$

$$(3.4) \quad T(\delta_i, \delta_j^\beta) = T_{j\ i}^{\beta k} \delta_k + T_{j\ i}^{\beta\alpha} \delta_\alpha + T_{j\ \delta i}^{\beta h} \delta_h^\delta,$$

where

$$\begin{aligned}
T_{j\ i}^{\beta k} &= \Gamma_{j\ i}^{\beta k} - \Gamma_{i\ j}^{k\beta} \\
T_{j\ i}^{\beta\alpha} &= \Gamma_{j\ i}^{\beta\alpha} - \Gamma_{i\ j}^{\alpha\beta} \\
T_{j\ \delta i}^{\beta h} &= \Gamma_{j\ \delta i}^{\beta h} - \Gamma_{i\ \delta j}^{h\beta} - K_{j\ \delta i}^{\beta h},
\end{aligned}$$

$$(3.5) \quad T(\delta_\alpha, \delta_\beta) = T_{\beta\alpha}^k \delta_k + T_{\beta\alpha}^\gamma \delta_\gamma + T_{\beta\delta\alpha}^h \delta_k^\delta,$$

where

$$T_{\beta\alpha}^k = \Gamma_{\beta\alpha}^k - \Gamma_{\alpha\beta}^k$$

$$T_{\beta\alpha}^\gamma = \Gamma_{\beta\alpha}^\gamma - \Gamma_{\beta\alpha}^\gamma$$

$$T_{\beta\delta\alpha}^h = \Gamma_{\beta\delta\alpha}^h - \Gamma_{\alpha\delta\beta}^h - K_{\beta\delta\alpha}^h$$

$$(3.6) \quad T(\delta_\alpha, \delta_j^\beta) = T_j^{\beta k} \delta_k + T_j^{\beta\gamma} \delta_\alpha + T_j^{\beta h} \delta_h^\delta,$$

where

$$T_j^{\beta k} \delta_k = \Gamma_j^{\beta k} \delta_k - \Gamma_{\alpha\beta}^{kj}$$

$$T_j^{\beta\gamma} \delta_\alpha = \Gamma_j^{\beta\gamma} \delta_\alpha - \Gamma_{\alpha j}^{\gamma\beta}$$

$$T_j^{\beta h} \delta_h^\delta = \Gamma_j^{\beta h} \delta_h^\delta - \Gamma_{\alpha\delta j}^{h\beta} - K_j^{\beta h} \delta_h^\delta$$

$$(3.7) \quad T(\delta_i^\alpha \delta_j^\beta) = T_j^{\beta k \alpha} \delta_h + T_j^{\beta\gamma \alpha} \delta_\gamma + T_j^{\beta h \alpha} \delta_h^\delta,$$

where

$$T_j^{\beta k \alpha} \delta_h = \Gamma_j^{\beta k \alpha} \delta_h - \Gamma_{i j}^{\alpha k \beta}$$

$$T_j^{\beta\gamma \alpha} \delta_\gamma = \Gamma_j^{\beta\gamma \alpha} \delta_\gamma - \Gamma_{i j}^{\alpha\gamma \beta}$$

$$T_j^{\beta h \alpha} \delta_h^\delta = \Gamma_j^{\beta h \alpha} \delta_h^\delta - \Gamma_{i \delta j}^{\alpha h \beta}$$

From the above we obtain

Theorem 3.1. *The torsion tensor in $T(E)$ for the linear connection ∇ is given by*

$$T(\delta_A, \delta_B) = T_B^k \delta_k + T_B^\gamma \delta_\gamma + T_{B\delta A}^k \delta_k^\delta,$$

$$A \in \{i, \alpha, \alpha_i\}, \quad B \in \{j, \beta, \beta_j\},$$

where

$$T_B^k \delta_k = \Gamma_B^k \delta_k - \Gamma_{AB}^k$$

$$T_B^\gamma \delta_\gamma = \Gamma_B^\gamma \delta_\gamma - \Gamma_{AB}^\gamma$$

$$T_{B\delta A}^k \delta_k^\delta = \Gamma_{B\delta A}^k \delta_k^\delta - \Gamma_{A\delta B}^k - K_{A\delta B}^k.$$

If we put $X = X^A \delta_A$, $Y = Y^B \delta_B$, then using the bilinearity of T we get

$$T(X, Y) = T_{B^C A}^C X^A Y^B \delta_C,$$

where

$$C \in \{k, \gamma, \overset{\delta}{h}\}$$

and the summation is going over all three types of indices. (If $C = \overset{\delta}{h}$ appears as upper index it becomes $\underset{\delta}{h}$).

Theorem 3.2. For the d -connection the torsion tensor has the form

$$\begin{aligned} (A) \quad (a) \quad T(\delta_i, \delta_j) &= T_j^k \delta_k - K_{j\delta_i}^k \delta_h^\delta, \quad T_j^k = \Gamma_{j i}^k - \Gamma_{i j}^k \\ (b) \quad T(\delta_i, \delta_\alpha) &= T_\alpha^\beta \delta_\beta - K_{\alpha\delta_i}^h \delta_h^\delta, \quad T_\alpha^\beta = \Gamma_{\alpha i}^\beta \\ (c) \quad T(\delta_i, \delta_j^\beta) &= T_j^{\beta k} \delta_k^\delta, \quad T_j^{\beta k} = \Gamma_{j \delta_i}^{\beta k} - K_{j \delta_i}^{\beta k} \\ (d) \quad T(\delta_\alpha, \delta_\beta) &= T_\beta^\gamma \delta_\gamma - K_{\beta\delta_\alpha}^h \delta_h^\delta, \quad T_\beta^\gamma = \Gamma_{\beta \alpha}^\gamma - \Gamma_{\alpha \beta}^\gamma \\ (e) \quad T(\delta_\alpha, \delta_j^\beta) &= T_j^{\beta k} \delta_k^\delta, \quad T_j^{\beta h} = \Gamma_{j \delta_\alpha}^{\beta h} - K_{j \delta_\alpha}^{\beta h} \\ (f) \quad T(\delta_i^\alpha, \delta_j^\beta) &= T_j^{\beta k \alpha} \delta_k^\delta, \quad T_j^{\beta k \alpha} = \Gamma_{j \delta_i}^{\beta k \alpha} - \Gamma_{i \delta_j}^{\alpha k \beta}. \end{aligned}$$

Theorem 3.3. For the $s.d.$ connection we have

$$\begin{aligned} (B) \quad (a) \quad T(\delta_i, \delta_j) &= T_j^k \delta_k - K_{j\delta_i}^k \delta_h^\delta, \quad T_j^k = \Gamma_{j i}^k - \Gamma_{i j}^k - \Gamma_{ij}^k \\ (b) \quad T(\delta_i, \delta_\alpha) &= -K_{\alpha\delta_i}^h \delta_h^\delta \\ (c) \quad T(\delta_i, \delta_j^\beta) &= -K_{j \delta_i}^{\beta k} \delta_k^\delta \\ (d) \quad T(\delta_\alpha, \delta_\beta) &= T_\beta^\gamma \delta_\gamma - K_{\beta\delta_\alpha}^h \delta_h^\delta, \quad T_\beta^\gamma = \Gamma_{\beta \alpha}^\gamma - \Gamma_{\alpha \beta}^\gamma \\ (e) \quad T(\delta_\alpha, \delta_j^\beta) &= -K_{j \delta_\alpha}^{\beta k} \delta_k^\delta \\ (f) \quad T(\delta_i^\alpha, \delta_j^\beta) &= T_j^{\beta k \alpha} \delta_k^\delta, \quad T_j^{\beta k \alpha} = \Gamma_{j \delta_i}^{\beta k \alpha} - \Gamma_{i \delta_j}^{\alpha k \beta}. \end{aligned}$$

4. The curvature tensor

In the space E the curvature tensor $R(X, Y)Z$ is defined as usually by

$$(4.1) \quad R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z.$$

If we use the notations

$$\begin{aligned} (4.2) \quad X &= X^A \delta_A = X^i \delta_i + X^\alpha \delta_\alpha + X_\alpha^i \delta_i^\alpha \\ Y &= Y^B \delta_B = Y^j \delta_j + Y^\beta \delta_\beta + Y_\beta^j \delta_j^\beta \\ Z &= Z^C \delta_C = Z^h \delta_h + Z^\gamma \delta_\gamma + Z_\gamma^h \delta_h^\gamma \end{aligned}$$

and the fact that R is linear with respect to all three components we get

$$(4.3) \quad R(X^A \delta_A, Y^B \delta_B) Z^C \delta_C = R(\delta_A, \delta_B) \delta_C X^A Y^B Z^C = R_{CBA}^D X^A Y^B Z^C \delta_D,$$

where

$$(4.4) \quad R_{CBA}^D \delta_D = R(\delta_A, \delta_B) \delta_C,$$

$$(4.5) \quad \begin{aligned} A &\in \{i, \alpha, {}^i_\alpha\}, & B &\in \{j, \beta, {}^j_\beta\} \\ C &\in \{k, \gamma, {}^k_\gamma\}, & D &\in \{k, \delta, {}^k_\delta\}. \end{aligned}$$

In (4.3) the summation is going over all three types of indices. From this fact it follows that on the right hand side of (4.3) there are 3^4 types of summands as:

$$\begin{aligned} &R_{hji}^k X^i Y^j Z^h \delta_k + R_{hja}^k X^\alpha Y^j Z^h \delta_k + \dots + \\ &+ R_{h\delta ji}^{\gamma k \beta \alpha} X^\alpha Y^\beta Z^\gamma \delta_k. \end{aligned}$$

If we use the shorter representation of (2.7) we can write:

$$\begin{aligned} \nabla_{\delta_B} \delta_C &= \Gamma_{CB}^D \delta_D, \\ \nabla_{\delta_A} \nabla_{\delta_B} \delta_C &= \{\delta_A \Gamma_{CB}^D + \Gamma_{CB}^E \Gamma_{EA}^D\} \delta_D. \end{aligned}$$

We denote

$$(4.6) \quad K_{CBA}^D \delta_D = \nabla_{\delta_A} \nabla_{\delta_B} \delta_C - \nabla_{\delta_B} \nabla_{\delta_A} \delta_C = [(\delta_A \Gamma_{CB}^D + \Gamma_{CB}^E \Gamma_{EA}^D) - (A/B)] \delta_D.$$

From (3.1) it follows

$$(4.7) \quad \begin{aligned} [\delta_A, \delta_B] &= K_{B\delta A}^h \delta_h^\delta \Rightarrow \\ \nabla_{[\delta_A, \delta_B]} \delta_C &= K_{B\delta A}^h \Gamma_C^D \delta_h^\delta \delta_D. \end{aligned}$$

From (4.4), (4.6) and (4.7) it follows

Theorem 4.1. *For the linear connection ∇ in space E the curvature tensor has the form*

$$(4.8) \quad R_{CBA}^D = K_{CBA}^D - K_{B\delta A}^h \Gamma_C^D \delta_h^\delta.$$

For indices A, B, C, D , (4.5) is valid.

As was mentioned before, that there are 3^4 types of curvature tensors; if $A = {}^i_\alpha$, $B = {}^j_\beta$ then $K_{j\delta i}^{\beta h \alpha} = 0$.

For the d -connection in (4.6) the indices C, D and E have to be of the same kind, so it follows

Theorem 4.2. *For the d -connection we have the following types of curvature tensor*

$$(4.9) \quad \begin{aligned} R_{h\ BA}^k &= K_{h\ BA}^k - K_{B\varepsilon A}^l \Gamma_{h\ l}^{k\varepsilon} \\ R_{\gamma\ BA}^\delta &= K_{\gamma\ BA}^\delta - K_{B\varepsilon A}^l \Gamma_{\gamma\ l}^{\delta\varepsilon} \\ R_{h\delta BA}^{\gamma k} &= K_{h\delta BA}^{\gamma k} - K_{B\varepsilon A}^l \Gamma_{h\ l}^{\gamma k\varepsilon}, \end{aligned}$$

where

$$\begin{aligned} K_{h\ BA}^k &= [(\delta_A \Gamma_{h\ B}^k + \Gamma_{h\beta B}^l \Gamma_{l\ A}^k) - (A/B)] \\ K_{\gamma\ BA}^\delta &= [(\delta_A \Gamma_{\gamma\ B}^\delta + \Gamma_{\gamma\ \varepsilon B}^\varepsilon \Gamma_{\varepsilon\ A}^\delta) - (A/B)] \\ K_{h\delta BA}^{\gamma k} &= [(\delta_A \Gamma_{h\ \delta B}^{\gamma k} + \Gamma_{h\ \varepsilon B}^l \Gamma_{l\ \delta A}^{\varepsilon k}) - (A/B)] \\ A &\in \{i, \alpha, \alpha^i\}, \quad B \in \{j, \beta, \beta^j\}. \end{aligned}$$

From the above it is obvious that for the d -connection there are $3 \cdot 3^2$ types of curvature tensors. When the indices A and B belong to T_2 , then the second terms on the right hand side in (4.8) are equal to zero.

Theorem 4.3. *For the s.d. connection we have the following types of curvature tensors:*

$$(4.10) \quad \begin{aligned} R_{h\ ji}^k &= K_{h\ ji}^k \\ R_{\gamma\ \beta\alpha}^\delta &= K_{\gamma\ \beta\alpha}^\delta \\ R_{h\ \delta ji}^{\gamma k\beta\alpha} &= K_{h\ \delta ji}^{\gamma k\beta\alpha}. \end{aligned}$$

where

$$\begin{aligned} K_{h\ ji}^k &= (\delta_i \Gamma_{h\ j}^k + \Gamma_{h\ j}^l \Gamma_{l\ h}^k) - (i/j) \\ K_{\gamma\ \beta\alpha}^\delta &= (\delta_\alpha \Gamma_{\gamma\ \beta}^\delta + \Gamma_{\gamma\ \beta}^\varepsilon \Gamma_{\varepsilon\ \alpha}^\delta) - (\alpha/\beta) \\ K_{h\ \delta ji}^{\gamma k\beta\alpha} &= (\delta_i^\alpha \Gamma_{h\ \delta j}^{\gamma k\beta} + \Gamma_{h\ \varepsilon j}^{\gamma l\beta} \Gamma_{l\ \delta i}^{\varepsilon k\alpha}) - (\alpha^i / j). \end{aligned}$$

For the s.d. connection all three indices in $\Gamma_{A\ C}^B$ are of the same type, the other are equal to zero and $K_{B\varepsilon A}^l = 0$, when A and B belong to T_2 .

If in the space E the metric tensor is given by (2.2) and $g_{ij} = g_{ij}(x)$, $g_{\alpha\beta} = g_{\alpha\beta}(t)$, $g_{i\ j}^{\alpha\beta} = g_{i\ j}^{\alpha\beta}(x_\gamma^b)$, then the connection coefficients

$$\Gamma_{i\ j}^k, \quad \Gamma_{\alpha\ \beta}^\gamma, \quad \Gamma_{i\ \beta\ k}^{\alpha\ j\gamma}$$

can be obtained as Cristoffel symbols of the corresponding metric tensors. In this case the connection coefficients are symmetric.

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Author's address:

Irena Čomić
Faculty of Technical Sciences, 21000 Novi Sad, Serbia & Montenegro
e-mail: comirena@uns.ns.ac.yu