Dual jet h-normal N-linear connections in time-dependent Hamilton geometry

M. Neagu, A. Oană and V. Balan

Abstract. In this paper we study the local adapted components of the h-normal N-linear connections in the dual jet time-dependent Hamilton geometry. The corresponding local d-torsions and d-curvatures are also analyzed.

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Key words: dual 1-jet space; d-tensors; *h*-normal *N*-linear connections; d-torsions; d-curvatures.

1 Introduction

The 1-jet spaces and their duals are the fundamental ambient spaces used in the study of classical and quantum field theories in the Lagrangian and Hamiltonian approaches (see Olver [8] and Atanasiu, Neagu and Oană [3]). Moreover, following the Cartan covariant Hamiltonian approach of classical Mechanics, the studies of Miron [4] and Atanasiu ([1], [2]) led to the development of the *Hamilton geometry of cotangent* bundles exposed by Miron, Hrimiuc, Shimada and Sabău in the monograph [5]. We underline that, via the Legendre duality of the Hamilton spaces with the Lagrange spaces, the preceding authors showed in [5] that the theory of Hamilton spaces has the same symmetry as the Lagrange geometry, giving thus a geometrical framework for the Hamiltonian theory of Analytical Mechanics.

In this physical and geometrical context, suggested by the cotangent bundle Miron's approach, the papers [6] and [7] are devoted to developing the *time-dependent covariant Hamilton geometry on dual 1-jet spaces* which is a natural dual jet extension of the Hamilton geometry on the cotangent bundle from [5]. The geometrical study from [6] and [7] of the usual objects as d-tensors, time-dependent semisprays of momenta, nonlinear connections, N-linear connections, d-torsions and d-curvatures is realized on the *dual 1-jet vector bundle* $J^{1*}(\mathbb{R}, M) \equiv \mathbb{R} \times T^*M \to \mathbb{R} \times M$, whose local coordinates are denoted by (t, x^i, p_i^1) . Here M^n is a smooth real manifold of dimension

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n, whose local coordinates are $(x^i)_{i=\overline{1,n}}$. Further, the coordinates p_i^1 are called momenta, and the dual 1-jet space $J^{1*}(\mathbb{R}, M)$ is called the *time-dependent phase space of momenta*.

The transformations of coordinates $(t, x^i, p_i^1) \longleftrightarrow (\tilde{t}, \tilde{x}^i, \tilde{p}_i^1)$, induced from $\mathbb{R} \times M$ on the dual 1-jet space $J^{1*}(\mathbb{R}, M)$, have the expressions

(1.1)
$$\begin{cases} \tilde{t} = \tilde{t}(t) \\ \tilde{x}^{i} = \tilde{x}^{i}(x^{j}) \\ \tilde{p}^{1}_{i} = \frac{\partial x^{j}}{\partial \tilde{x}^{i}} \frac{d\tilde{t}}{dt} p^{1}_{j}, \end{cases}$$

where $d\tilde{t}/dt \neq 0$ and $\det(\partial \tilde{x}^i/\partial x^j) \neq 0$. Consequently, in the present dual jet geometrical approach, we use a kind of "relativistic" time t.

For instance, in the Hamiltonian Miron's approach from [5], the authors use the trivial bundle $\mathbb{R} \times T^*M \to T^*M$, whose local coordinates induced by T^*M are (t, x^i, p_i) . Thus, the changes of coordinates are given by relations

$$\begin{cases} \tilde{t} = t \\ \tilde{x}^{i} = \tilde{x}^{i} \left(x^{j} \right) \\ \tilde{p}_{i} = \frac{\partial x^{j}}{\partial \tilde{x}^{i}} p_{j}, \end{cases}$$

pointing out the *absolute* character of the time variable t.

A geometrization of Hamiltonians $H : \mathbb{R} \times T^*M \to \mathbb{R}$ on the dual 1-jet vector bundle $J^{1*}(\mathbb{R}, M) \equiv \mathbb{R} \times T^*M \to \mathbb{R} \times M$ was initiated in the papers [6] and [7] and it is in progress in this paper and other future articles.

2 h-Normal N-linear connections

Generally speaking, a linear connection on the dual 1-jet space $J^{1*}(\mathbb{R}, M)$ is characterized by 27 adapted local components. To work with these components is very complicated through of the big numbers of coefficients. For this reason, in the paper [7], were introduced and studied the N-linear connections. Because the number of components which characterize an N-linear connection on $E^* = J^{1*}(\mathbb{R}, M)$ is still a big one (9 local components), we are constrained to study only a particular class of N-linear connections on E^* , which must be characterized by a reduced number of components. In this direction, let us consider a semi-Riemannian metric $h_{11}(t)$ on the time manifold \mathbb{R} , together with its Christoffel symbol

$$\chi_{11}^1 = \frac{h^{11}}{2} \frac{dh_{11}}{dt}.$$

Let \mathbb{J} be the *h*-normalization d-tensor field on E^* , locally expressed by $\mathbb{J} = J_{(1)1j}^{(i)} \delta p_i^1 \otimes dt \otimes dx^j$, where $J_{(1)1j}^{(i)} = h_{11} \delta_j^i$. In this context, we introduce the following geometrical concept:

Definition 2.1. An N-linear connection $D\Gamma(N)$ on E^* , whose local components

$$D\Gamma(N) = \left(A_{11}^{1}, A_{j1}^{i}, -A_{(i)(1)}^{(1)(j)}, H_{1k}^{1}, H_{jk}^{i}, -H_{(i)(1)k}^{(1)(j)}\right)$$
$$C_{1(1)}^{1(k)}, C_{j(1)}^{i(k)}, -C_{(i)(1)(1)}^{(1)(k)}\right),$$

satisfy the relations $A_{11}^1 = \chi_{11}^1$, $H_{1i}^1 = 0$, $C_{1(1)}^{1(i)} = 0$ and $D\mathbb{J} = 0$, is called an *h*-normal *N*-linear connection on the dual 1-jet space E^* .

Theorem 2.1. The local adapted components of an h-normal N-linear connection $D\Gamma(N)$ verify the following identities:

(2.1)
$$A_{11}^{1} = \chi_{11}^{1}, \quad H_{1i}^{1} = 0, \quad C_{1(1)}^{1(i)} = 0,$$
$$A_{(i)(1)1}^{(1)(j)} = A_{i1}^{j} - \delta_{i}^{j} \chi_{11}^{1}, \quad H_{(i)(1)k}^{(1)(j)} = H_{ik}^{j},$$
$$C_{(i)(1)(1)}^{(1)(j)(k)} = C_{i(1)}^{j(k)}.$$

Proof. It is obvious that the first three relations immediately come from the definition of an *h*-normal *N*-linear connection. To prove the other three relations, we emphasize that, taking into account the definition of the local \mathbb{R} -horizontal $\binom{n}{1}$, *M*-horizontal $\binom{n}{|s|}$ and vertical $\binom{n}{|s|}$ covariant derivatives produced by $D\Gamma(N)$, the condition $D\mathbb{J} = 0$ is equivalent to

$$J_{(1)1j/1}^{(i)} = 0, \qquad J_{(1)1j/s}^{(i)} = 0, \qquad J_{(1)1j}^{(i)}|_{(1)}^{(s)} = 0.$$

Consequently, the condition $D\mathbb{J} = 0$ provides the local identities

$$h_{11}A_{(j)(1)1}^{(1)(i)} = h_{11}A_{j1}^{i} - \delta_{j}^{i} \left(\frac{dh_{11}}{dt} - h_{11}\chi_{11}^{1}\right) = h_{11}A_{j1}^{i} - \delta_{j}^{i}\frac{1}{2}\frac{dh_{11}}{dt},$$

$$h_{11}H_{(j)(1)k}^{(1)(i)} = h_{11}H_{jk}^{i}, \quad h_{11}C_{(j)(1)(1)}^{(1)(i)(k)} = h_{11}C_{j(1)}^{i(k)}.$$

Contracting now the above relations by h^{11} , we obtain the last required identities from (2.1).

Remark 2.2. The above Theorem shows that an *h*-normal *N*-linear connection on E^* is an *N*-linear connection determined only by *four* effective components (instead of nine in the general case):

$$D\Gamma(N) = \left(\chi_{11}^1, \ A_{j1}^i, \ H_{jk}^i, \ C_{j(1)}^{i(k)}\right).$$

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The other five components either vanish or are provided by the relations (2.1).

Example 2.3. The Berwald N_0 -linear connection associated with the pair of metrics $(h_{11}(t), \varphi_{ij}(x))$ is an *h*-normal N_0 -linear connection on E^* , whose four effective components are $B\Gamma(N_0) = (\chi_{11}^1(t), 0, \gamma_{jk}^i(x), 0)$, where $\gamma_{jk}^i(x)$ are the Christoffel symbols of the metric $\varphi_{ij}(x)$. For more details, see the papers [6] and [7].

3 Torsion and curvature d-tensors

The study of the adapted components of the torsion and curvature tensors of an arbitrary N-linear connection $D\Gamma(N)$ on E^* was done in [7]. In that context, it turned out that the torsion tensor **T** is determined by *ten* effective local adapted d-tensors, while the curvature tensor **R** is determined by *fifteen* local adapted d-tensors. In what follows, we study the adapted components of the torsion and curvature tensors for an h-normal N-linear connection $D\Gamma(N)$.

Theorem 3.1. The torsion tensor \mathbf{T} of an h-normal N-linear connection $D\Gamma(N)$ is determined by eight effective local adapted d-tensors (instead of ten in the general case):

	$h_{\mathbb{R}}$	h_M	v
$h_{\mathbb{R}}h_{\mathbb{R}}$	0	0	0
$h_M h_{\mathbb{R}}$	0	T^r_{1j}	$R_{(r)1j}^{(1)}$
$vh_{\mathbb{R}}$	0	0	$P_{(r)1(1)}^{(1)(j)}$
$h_M h_M$	0	T^r_{ij}	$R^{(1)}_{(r)ij}$
vh_M	0	$P_{i(1)}^{r(j)}$	$P_{(r)i(1)}^{(1)(j)}$
vv	0	0	$S^{(1)(i)(j)}_{(r)(1)(1)}$

where

(3.1)

$$\begin{split} T_{1j}^r &= -A_{j1}^r, \quad T_{ij}^r = H_{ij}^r - H_{ji}^r, \quad P_{i(1)}^{r(j)} = C_{i(1)}^{r(j)}, \\ P_{(r)1(1)}^{(1)} &= \frac{\partial N_{(r)1}^{(1)}}{\partial p_i^1} + A_{r1}^j - \delta_r^j \chi_{11}^1, \quad P_{(r)i(1)}^{(1)} = \frac{\partial N_{(r)i}^{(1)}}{\partial p_i^1} + H_{ri}^j, \end{split}$$

$$R_{(r)1j}^{(1)} = \frac{\delta N_{(r)1}^{(1)}}{\delta x^j} - \frac{\delta N_{(r)j}^{(1)}}{\delta t},$$

$$R_{(r)ij}^{(1)} = \frac{\delta N_{2}^{(1)}}{\delta x^{j}} - \frac{\delta N_{2}^{(1)}}{\delta x^{i}}, \quad S_{(r)(1)(1)}^{(1)(j)} = -\left(C_{r(1)}^{i(j)} - C_{r(1)}^{j(i)}\right).$$

Proof. Particularizing the general local expressions of the torsion tensor of an *N*-linear connection from [7] (which generally have ten d-components) for an *h*-normal *N*-linear connection $D\Gamma(N)$ on E^* , we deduce that the adapted components T_{1j}^1 and $P_{1(1)}^{1(k)}$ are zero, while the other eight are given by the formulas from Theorem. \Box

Remark 3.1. All torsion d-tensors of the Berwald *h*-normal N_0 -linear connection $B\Gamma(N_0)$ (associated with the semi-Riemannian metrics $h_{11}(t)$ and $\varphi_{ij}(x)$) are zero, except $R^{(1)}_{(r)ij} = -\Re^s_{rij}p^1_s$, where $\Re^s_{rij}(x)$ are the local curvature tensors of the metric $\varphi_{ij}(x)$.

	$h_{\mathbb{R}}$	h_M	v
$h_{\mathbb{R}}h_{\mathbb{R}}$	0	0	0
$h_M h_{\mathbb{R}}$	0	R_{i1k}^l	$-R_{(l)(1)1k}^{(1)(i)} = -R_{l1k}^{i}$
$wh_{\mathbb{R}}$	0	$P_{i1(1)}^{l\ (k)}$	$-P_{(l)(1)1(1)}^{(1)(i)}(k) = -P_{l1(1)}^{i(k)}$
$h_M h_M$	0	R^l_{ijk}	$-R_{(l)(1)jk}^{(1)(i)} = -R_{ljk}^{i}$
wh_M	0	$P_{ij(1)}^{l\ (k)}$	$-P_{(l)(1)j(1)}^{(1)(i)} = -P_{lj(1)}^{i(k)}$
ww	0	$S_{i(1)(1)}^{l(j)(k)}$	$-S_{(l)(1)(1)(1)}^{(1)(i)(j)(k)} = -S_{l(1)(1)}^{i(j)(k)}$

Theorem 3.2. The curvature tensor **R** of an h-normal N-linear connection $D\Gamma(N)$ is characterized by five effective local d-tensors (instead of fifteen in the general case):

where

(3.2)

$$\begin{split} R^{l}_{i1k} &= \frac{\delta A^{l}_{i1}}{\delta x^{k}} - \frac{\delta H^{l}_{ik}}{\delta t} + A^{r}_{i1}H^{l}_{rk} - H^{r}_{ik}A^{l}_{r1} + C^{l(r)}_{i(1)}R^{(1)}_{(r)1k}, \\ P^{l}_{i1(1)} &= \frac{\partial A^{l}_{i1}}{\partial p^{1}_{k}} - C^{l(k)}_{i(1)/1} + C^{l(r)}_{i(1)}P^{(1)}_{(r)1(1)}, \\ R^{l}_{ijk} &= \frac{\delta H^{l}_{ij}}{\delta x^{k}} - \frac{\delta H^{l}_{ik}}{\delta x^{j}} + H^{r}_{ij}H^{l}_{rk} - H^{r}_{ik}H^{l}_{rj} + C^{l(r)}_{i(1)}R^{(1)}_{(r)jk}, \\ P^{l}_{ij(1)} &= \frac{\partial H^{l}_{ij}}{\partial p^{1}_{k}} - C^{l(k)}_{i(1)|j} + C^{l(r)}_{i(1)}P^{(1)}_{(r)j(1)}, \\ S^{l(j)(k)}_{i(1)(1)} &= \frac{\partial C^{l(j)}_{i(1)}}{\partial p^{1}_{k}} - \frac{\partial C^{l(k)}_{i(1)}}{\partial p^{1}_{j}} + C^{r(j)}_{i(1)}C^{l(k)}_{r(1)} - C^{r(k)}_{i(1)}C^{l(j)}_{r(1)}. \end{split}$$

Proof. The general formulas which express the local curvature d-tensors of an arbitrary N-linear connection from [7], applied to the particular case of an h-normal N-linear connection $D\Gamma(N)$, imply the above formulas and the relations from the Table (3.2).

Remark 3.2. For the Berwald *h*-normal N_0 -linear connection $B\Gamma(N_0)$ (associated with the pair of metrics $(h_{11}(t), \varphi_{ij}(x)))$, all curvature d-tensors are zero, except $R_{(i)(1)jk}^{(1)(l)} = R_{ijk}^l = \mathfrak{R}_{ijk}^l$.

4 A physical application

As an example, we shall investigate in a forecoming paper, the *dual jet time-dependent Hamiltonian of electrodynamics*,

(4.1)
$$H = \frac{1}{4mc} h_{11}(t) \varphi^{ij}(x) p_i^1 p_j^1 - \frac{e}{m^2 c} A^{(i)}_{(1)}(x) p_i^1 + \frac{e^2}{m^3 c} F(t,x) - \mathsf{P}(t,x),$$

where $A_{(1)}^{(i)}(x)$ is a d-tensor on $J^{1*}(\mathbb{R}, M)$ having the physical meaning of a *potential* d-tensor of an electromagnetic field, P(t, x) is a *potential function*, and m, c and e are well-known physical constants: mass of the test body, speed of light and electric

charge. Here, we have $F(t,x) = h^{11}(t)\varphi_{ij}(x)A^{(i)}_{(1)}(x)A^{(j)}_{(1)}(x)$. The geometrization associated with this time-dependent Hamiltonian will consist of a canonical nonlinear connection N, a Cartan canonical N-linear connection $C\Gamma(N)$ (which is an h-normal linear connection) together with its adapted d-torsions and d-curvatures. All these geometrical objects are provided only by the time-dependent Hamiltonian (4.1).

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Authors' addresses:

Mircea Neagu, Alexandru Oană Transilvania University of Braşov, Department of Mathematics and Informatics, Blvd. Iuliu Maniu 50, 500091 Braşov, Romania. E-mail: mircea.neagu@unitbv.ro, alexandru.oana@unitbv.ro

Vladimir Balan University Politehnica of Bucharest, Faculty of Applied Sciences, Department of Mathematics - Informatics, 313 Splaiul Independentei, Bucharest 060042, Romania. E-mail: vladimir.balan@upb.ro