

# From curves to extrema, continuity and convexity

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**Abstract.** Section 1 relates the continuity, extrema and convexity to the unidimensional constraints. Section 2 study the convexity of Monge hypersurfaces along parametrized curves.

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**Key words:** free extrema, unidimensional constraints, convexity along curves.

## 1 Continuity, extrema and convexity by curves

This section develops some results of the authors [1]-[18] regarding the extrema constrained by curves and gives new and interesting results by Theorems 2.6, 2.7, 2.8. To formulate these new results, we start with an open set  $D$  in  $\mathbf{R}^p$ , a function  $f : D \rightarrow \mathbf{R}$ , a point  $a \in D$  and a family  $\Gamma_a$  of parametrized curves  $\alpha : I \rightarrow D$  passing through the point  $a = \alpha(t_0)$ .

**2.1. Definition.** We say that  $a$  is a extremum point for  $f$  constrained by  $\alpha$ , if  $t_0$  is an extremum point for  $f \circ \alpha$ . We say that  $a$  is a minimum (maximum) point for  $f$  constrained by  $\Gamma_a$ , if  $a$  is a minimum (maximum) point for  $f$  constrained by each  $\alpha \in \Gamma_a$ .

**2.2. Definition.** We say that the point  $f(a)$  is a separator for the values of the function  $f$  along  $\alpha$ , if there exists  $\varepsilon > 0$  such that  $f(\alpha(t)) \geq f(a)$  ( $f(\alpha(t)) \leq f(a)$ ),  $\forall t \in (t_0 - \varepsilon, t_0]$  and  $f(\alpha(t)) \leq f(a)$  ( $f(\alpha(t)) \geq f(a)$ ),  $\forall t \in [t_0, t_0 + \varepsilon)$ .

**2.3. Definition.** We say that the function  $f$  is locally (strict) convex at  $a$  along  $\alpha$ , if  $f(\alpha(tu + (1-t)t_0)) \leq (<)tf(\alpha(u)) + (1-t)f(a)$  for  $u$  in a neighborhood of  $t_0$  and  $t \in (0, 1)$ .

For the next theorems we suppose that, the family  $\Gamma_a$  is either the set of all  $C^1$  parametrized curves passing through  $a$  and regular at  $a$  or the family of all  $C^2$  parametrized curves passing through  $a$ , such that either  $a$  is a regular point for  $\alpha$ , or  $a$  is a singular point of the second order for  $\alpha$ .

**2.4. Theorem ([9],[11]).** *Let  $(x_n)$  be a sequence of distinct points in  $\mathbf{R}^p$  such that  $x_n \rightarrow a \in \mathbf{R}^p$ . Then there exists a parametrized curve  $\alpha : \mathbf{R} \rightarrow \mathbf{R}^p$  from the family  $\Gamma_a$ , a subsequence  $(x_{n_k})$  of  $(x_n)$  and a strictly decreasing sequence  $(t_k)$  of real numbers such that*

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- 1)  $\alpha(0) = 0$ , and  
 2)  $t_k \rightarrow 0$  and  $\alpha(t_k) = x_{n_k}$ ,  $\forall k \in \mathbf{N}$ .

Consequently we get

**2.5. Theorem.** *Let  $f : D \rightarrow \mathbf{R}$  and  $a \in D$ . The point  $a$  is a minimum (maximum) point for  $f$  if and only if  $a$  is a minimum (maximum) point for  $f$  constrained by  $\Gamma_a$ .*

To formulate a refined result we need

**2.6. Theorem.** *Let  $f : D \subset \mathbf{R}^p \rightarrow \mathbf{R}$  and  $a \in D$ . Suppose that for each  $\alpha \in \Gamma_a$  ( $\alpha(t_0) = a$ ),  $f \circ \alpha$  is continuous at  $t_0$ . Then  $f$  is continuous at  $a$ .*

*Proof.* Suppose, per absurdum, that  $f$  is not continuous at  $a$ , i.e., there exists a sequence  $(x_n)$  from  $D$  with  $x_n \rightarrow a$  and  $f(x_n) \rightarrow l$ , with  $l \neq f(a)$ . According to theorem 2.4, there exists a parametrized curve  $\alpha \in \Gamma_a$ , a subsequence  $(x_{n_k})$  and a sequence of real numbers  $(t_{n_k})$ ,  $t_{n_k} \rightarrow 0$  such that  $\alpha(t_{n_k}) = x_{n_k}$  and  $\alpha(0) = a$ . From the continuity of  $f \circ \alpha$  at 0, we obtain that  $f(x_{n_k}) \rightarrow f(a)$ , which is a contradiction.

**2.7. Theorem.** *Let  $f : D \subset \mathbf{R}^p \rightarrow \mathbf{R}$  and  $a \in D$ . Suppose that  $f \circ \alpha$  is continuous for each  $\alpha \in \Gamma_a$ , and  $a$  is a strict extremum point constrained by  $\alpha$ . Then  $a$  is a strict extremum point for  $f$ .*

*Proof.* From the previous theorem it follows that  $f$  is continuous. Let suppose that  $a$  is a strict extremum point for  $f$  constrained by each  $\alpha \in \Gamma_a$ . We prove that  $a$  is a strict extremum point for  $f$  constrained by  $\Gamma_a$ . In this way, according to theorem 2.5, it follows that  $a$  is a point of strict extremum for  $f$ .

Suppose, per absurdum, that there exist two parametrized curves  $\alpha : I \rightarrow D$  and  $\beta : J \rightarrow D$  in  $\Gamma_a$  ( $a = \alpha(t_0) = \beta(u_0)$ ) such that  $a$  is a point of strict minimum for  $f$  constrained by  $\alpha$ , and in the same time  $a$  is a point of strict maximum for  $f$  constrained by  $\beta$ .

Hence we can find two sequences of real numbers  $(t_n)$  and  $(u_n)$ ,  $t_n \rightarrow t_0$  and  $u_n \rightarrow u_0$ , such that  $f(\alpha(t_n)) > f(a)$  and  $f(\beta(u_n)) < f(a)$ . From the continuity of  $f$  it follows that on the segment  $[\alpha(t_n), \beta(u_n)]$  in  $\mathbf{R}^p$  we can find a point  $x_n$  with  $f(x_n) = f(a)$ . Applying theorem 2.4 to the sequence  $(x_n)$ , we get a parametrized curve  $\gamma$  in  $\Gamma_a$ , a subsequence  $(x_{n_k})$  of  $(x_n)$  and a sequence of real numbers  $(q_k)$  such that  $q_k \rightarrow 0$ ,  $\gamma(0) = a$  and  $\gamma(q_k) = x_{n_k}$ . It follows  $f(\gamma(q_k)) = f(a)$ ,  $\forall k \in \mathbf{N}$ , i.e., the point  $a$  cannot be a strict extremum point for  $f$  constrained by  $\gamma$ . This result is a contradiction.

**Remark.** The previous theorems hold for the case in which  $\mathbf{R}^p$  is replaced by a finite dimensional differentiable manifold.

**2.8. Theorem.** *Let  $f : D \rightarrow \mathbf{R}$  and  $a \in D$  such that*

- i)  $f$  is differentiable
- ii) For any  $\alpha \in \Gamma_a$  the point  $f(a)$  is not a separator point along  $\alpha$ .
- iii) For any  $\alpha \in \Gamma_a$  it follows that  $f$  or  $-f$  is locally strict convex at  $a$  along  $\alpha$ . In these conditions  $a$  is a point of strict extremum of  $f$ , and  $f$  or  $-f$  is locally convex at  $a$ .

*Proof.* Let  $\alpha \in \Gamma_a$  ( $\alpha(t_0) = a$ ). Because  $f(a)$  is not a separator point along  $\alpha$ , it follows that there exists two sequences  $(u_n)$  and  $(v_n)$  with  $u_n < t_0 < v_n$  having the limit  $t_0$  such that  $f(\alpha(u_n)) \leq f(a)$ ,  $f(\alpha(v_n)) \geq f(a)$  or  $f(\alpha(u_n)) \leq f(a)$ ,  $f(\alpha(v_n)) \leq f(a)$ ,  $n \in \mathbf{N}$ . Because  $\varphi(t) = f(\alpha(t))$  is differentiable, it follows that  $\varphi'(t_0) = 0$ . Because  $\varphi$  or  $-\varphi$  is locally convex at  $t_0$ , it follows that  $t_0$  is a strict extremum point of  $\varphi$  (minimum or maximum). Thus we get that  $a$  is a strict extremum point of  $f$  constrained by each  $\alpha \in \Gamma_a$ . In accordance with theorem 2.7  $a$  is a strict extremum

point of  $f$ . Thus,  $f$  is locally strict convex at  $a$  along any parametrized curve  $\alpha \in \Gamma_a$ , or  $-f$  is locally strict convex at  $a$  along any parametrized curve  $\alpha \in \Gamma_a$ . It follows that  $f$  or  $-f$  is locally strict convex at  $a$ .

## 2 Convexity of Monge hypersurfaces

Let  $f : D \subset \mathbf{R}^{p-1} \rightarrow \mathbf{R}$  be a function of reasonable class, and  $\Sigma : x^p = f(x_1, \dots, x_{p-1})$  a Monge hypersurface in  $\mathbf{R}^p$ . Let  $a \in D$  and  $\Gamma_a$  the family of parametrized curves specified in the previous section.

**3.1. Theorem.** *Suppose that for any  $\alpha \in \Gamma_a$ , the point  $a$  is a strict extremum point restricted by  $\alpha$ . Then the hyperplane  $x^p = f(a)$  is tangent to  $\Sigma$  at  $(a, f(a))$ , and  $\Sigma$  is locally strict convex at  $(a, f(a))$ , i.e., around  $(a, f(a))$  the Monge hypersurface  $\Sigma$  rests strictly on the same side of the tangent hyperplane.*

This theorem follows from theorem 2.7.

**3.2. Theorem.** *Suppose that  $f$  or  $-f$  is locally strict convex at  $a$  along any  $\alpha \in \Gamma_a$  and  $f(a)$  is not a separator point of  $f$  along  $\alpha$ . In these conditions the hyperplane  $x^p = f(a)$  is a tangent hyperplane to  $\Sigma$  at  $(a, f(a))$ , and  $\Sigma$  is locally strict convex at  $a$ .*

This theorem follows directly from theorem 2.8.

In the sequel we suppose that  $x^p = f(a)$  is the tangent hyperplane to  $\Sigma$  at  $(a, f(a))$ . This hyperplane can be identified with  $\mathbf{R}^{p-1}$ , and the point  $(a, f(a))$  with  $a$ . Let  $\Gamma_a^*$  be the family of all parametrized curves passing through  $a$  and contained in  $\Sigma$ , having the same properties as those for the family  $\Gamma_a$ .

**3.3. Lemma.** *The following statements hold true:*

i) *Let  $\alpha$  be a parametrized curve passing through  $a$  and contained in the tangent hyperplane at  $a$ . Then  $\alpha \in \Gamma_a$  if and only if  $(\alpha, f \circ \alpha) \in \Gamma_a^*$ .*

ii) *The association  $\alpha \rightarrow (\alpha, f \circ \alpha)$  is a bijective correspondence between  $\Gamma_a$  and  $\Gamma_a^*$ .*

iii)  *$a$  is a strict extremum point of  $f$  constrained by  $\alpha$  if and only if the parametrized curve  $(\alpha, f \circ \alpha)$  rests, around  $a$ , on the same side of the tangent hyperplane at  $a$ .*

*Proof.* We prove the sentence ii). It is obvious that the association  $\alpha \rightarrow (\alpha, f \circ \alpha)$  is one-to-one. Let  $\beta \in \Gamma_a^*$  ( $\beta(0) = \alpha$ ). It follows that  $\beta(t) = (\alpha(t), (f \circ \alpha)(t))$ , where  $\alpha$  is the projection of  $\beta$  on the tangent hyperplane. Let us prove that  $\alpha \in \Gamma_a$ . We have

$$\beta'(t) = \left( \alpha'(t), \sum_{i=1}^{p-1} \frac{\partial f}{\partial x^i}(\alpha(t)) \frac{dx^i}{dt}(t) \right)$$

and

$$\beta''(t) = \left( \alpha''(t), \sum_{i=1}^{p-1} \frac{\partial f}{\partial x^i}(\alpha(t)) \frac{d^2 x^i}{dt^2}(t) + \sum_{i,j=1}^{p-1} \frac{\partial^2 f}{\partial x^i \partial x^j}(\alpha(t)) \frac{dx^i}{dt}(t) \frac{dx^j}{dt}(t) \right).$$

Because  $\frac{\partial f}{\partial x^i}(\alpha(0)) = 0$ , we obtain  $\beta'(0) = (\alpha'(0), 0)$  and

$$\beta''(0) = \left( \alpha''(0), \sum_{i,j=1}^{p-1} \frac{\partial^2 f}{\partial x^i \partial x^j}(\alpha(0)) \frac{dx^i}{dt}(0) \frac{dx^j}{dt}(0) \right).$$

If  $\alpha'(0) = 0$  we obtain  $\beta'(0) = 0$  and thus  $\beta''(0) = (\alpha''(0), 0)$ . As  $\beta''(0) \neq 0$  we have  $\alpha''(0) \neq 0$ .

**3.4. Definition.** We say that the hypersurface  $\Sigma$  is (strictly) convex at  $a$  along a parametrized curve  $\alpha \in \Gamma_a$  if  $a$  is a point of (strict) extremum for  $f$  restricted by  $\alpha$ . Also, we say that  $\Sigma$  is (strictly) convex at  $a$  with respect to the family  $\Gamma_a$  if  $a$  is a (strict) extremum point of  $f$  constrained by  $\Gamma_a$ .

**3.5. Theorem.** *The hypersurface  $\Sigma$  is strictly convex at  $a$  with respect to the family  $\Gamma_a$  if and only if  $\Sigma$  is strictly convex at  $a$  along any parametrized curve  $\alpha$  in  $\Gamma_a$ .*

This theorem is a direct consequence of theorem 2.5.

In the sequel let suppose that the hypersurface  $\Sigma$  is defined by the Cartesian implicit equation  $F(x_1, \dots, x_p) = 0$ . Let

$$g(x) = \sum_{i=1}^p \frac{\partial F}{\partial x^i}(a)(x^i - a^i)$$

be the linear approximation of  $F$  around the point  $a$ .

**3.6. Definition.** We say that the hypersurface  $\Sigma$  is (strictly) convex at  $a$  along the parametrized curve  $\alpha \in \Gamma_a^*$  if  $a$  is a (strict) extremum point for  $g$  restricted by  $\alpha$ . Also, we say that  $\Sigma$  is (strictly) convex at  $a$  with respect to the family  $\Gamma_a^*$  if  $a$  is a (strict) extremum point of  $g$  restricted by the family  $\Gamma_a^*$ .

Summing the previous results, we obtain:

**3.7. Theorem.** *The following statements are equivalent:*

- a)  $\Sigma$  is strictly convex at  $a$  along any parametrized curve in  $\Gamma_a$ ;
- b)  $\Sigma$  is strictly convex at  $a$  along any parametrized curve in  $\Gamma_a^*$ ;
- c)  $\Sigma$  is strictly convex at  $a$  with respect to the family  $\Gamma_a$ ;
- d)  $\Sigma$  is strictly convex at  $a$  with respect to the family  $\Gamma_a^*$ ;
- e) The point  $a$  is a strict extremum point of the function  $g$  restricted to  $\Sigma$ .

Reformulating:

**3.8. Theorem.** *The following statements are equivalent:*

- a) Each parametrized curve in the family  $\Gamma_a^*$  rests, around  $a$ , strictly on the same side of the tangent hyperplane to  $\Sigma$  at  $a$ .
- b) All the parametrized curves in the family  $\Gamma_a^*$  rest, around  $a$ , strictly on the same side of the tangent hyperplane to  $\Sigma$  at  $a$ .
- c) The hypersurface  $\Sigma$  rests, around  $a$ , on the same side of the tangent hyperplane to  $\Sigma$  at  $a$ .

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