

Warped product semi-slant submanifolds of trans-Sasakian manifolds

Siraj Uddin and Khalid Ali Khan

Abstract. In the present paper, we study warped product semi-slant submanifolds of trans-Sasakian manifolds. We have obtained results on the existence of warped product semi-slant submanifolds of trans-Sasakian manifolds in term of the canonical structure F .

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1 Introduction

The notion of semi-slant submanifolds of almost Hermitian manifolds was introduced by N. Papaghuic [14]. In fact, semi-slant submanifolds in almost Hermitian manifolds are defined on the line of CR-submanifolds. In the setting of almost contact metric manifolds, semi-slant submanifolds are defined and investigated by J.L. Cabrerizo et. al [4].

In [13] J.A. Oubina studied a new class of almost contact metric structure, called *trans-Sasakian* which is, in some sense, an analogue of a locally conformal Kaehler structure on an almost Hermitian manifold.

On the other hand, in Gray-Hervella classification of almost Hermitian manifolds [7], there appears a class \mathcal{W}_4 , of Hermitian manifolds which are closely related to a locally conformal Kaehler manifolds. An almost contact metric structure on a manifold \bar{M} is called *trans-Sasakian* structure [13] if the product manifold $\bar{M} \times \mathbb{R}$ belongs to class \mathcal{W}_4 . In [6], the authors introduced two subclasses of trans-Sasakian structure, the \mathcal{C}_5 and \mathcal{C}_6 -structures, which contains the Kenmotsu and Sasakian structures, respectively. The class $\mathcal{C}_6 \oplus \mathcal{C}_5$ [11] coincides with the class of trans-Sasakian of type (α, β) . We note that the trans-Sasakian structures of type $(0, 0)$, $(0, \beta)$ and $(\alpha, 0)$ are cosymplectic [3], β -Kenmotsu and α -Sasakian [8], respectively.

Warped product manifolds were introduced by R.L. Bishop and B. O'Neill in [2]. The problem of existence or non-existence of warped product manifolds plays some important role in differential geometry and physics. The study of warped product semi-slant submanifolds of Kaehler manifolds was introduced by B. Sahin [15]. Later, K.A. Khan et.al studied warped product semi-slant submanifolds in cosymplectic

manifolds and showed that there exist no proper warped product semi-slant submanifolds in the forms $N_T \times_f N_\theta$ and reversing the two factors in cosymplectic manifolds [9].

Recently, M. Atçeken proved that the warped product submanifolds of the types $M = N_\theta \times_f N_T$ and $M = N_\theta \times_f N_\perp$ of a Kenmotsu manifold \bar{M} do not exist where the manifolds N_θ and N_T (resp. N_\perp) are proper slant and ϕ -invariant (resp. anti-invariant) submanifolds of a Kenmotsu manifold \bar{M} , respectively [1]. In this paper, we have obtained some results for the existence of warped product semi-slant submanifolds of trans-Sasakian manifolds.

2 Preliminaries

Let \bar{M} be a $(2m + 1)$ -dimensional manifold with almost contact structure (ϕ, ξ, η) is defined on \bar{M} by a $(1, 1)$ tensor field ϕ , a vector field ξ and the dual 1-form η of ξ , satisfying the following properties [3]

$$(2.1) \quad \phi^2 = -I + \eta \otimes \xi, \quad \phi\xi = 0, \quad \eta \circ \phi = 0, \quad \eta(\xi) = 1.$$

There always exists a Riemannian metric g on an almost contact manifold \bar{M} satisfying the following compatibility condition

$$(2.2) \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y).$$

An almost contact structure (ϕ, ξ, η) is said to be *normal* if the almost complex structure J on the product manifold $\bar{M} \times \mathbb{R}$ given by

$$J(X, f \frac{d}{dt}) = (\phi X - f\xi, \eta(X) \frac{d}{dt}),$$

has no torsion i.e., J is integrable where f is a C^∞ -function on $\bar{M} \times \mathbb{R}$, in other words the tensor $[\phi, \phi] + 2d\eta \otimes \xi$ vanishes identically on \bar{M} , where $[\phi, \phi]$ is the Nijenhuis tensor of ϕ [17].

An almost contact metric manifold \bar{M} is called *trans-Sasakian* [13] if

$$(2.3) \quad (\bar{\nabla}_X \phi)Y = \alpha\{g(X, Y)\xi - \eta(Y)X\} + \beta\{g(\phi X, Y)\xi - \eta(Y)\phi X\}.$$

for all $X, Y \in T\bar{M}$, where α, β are smooth function on \bar{M} and $\bar{\nabla}$ is the Levi-Civita connection of g and in this case we say that the *trans-Sasakian structure* is of type (α, β) .

If $\alpha = 0$ then \bar{M} is β -Kenmotsu manifold and if $\beta = 0$ then \bar{M} is α -Sasakian manifold. Moreover, if $\alpha = 1$ and $\beta = 0$ then \bar{M} is a *Sasakian* manifold and if $\alpha = 0$ and $\beta = 1$ then \bar{M} is a *Kenmotsu* manifold. From (2.3), it follows that

$$(2.4) \quad \bar{\nabla}_X \xi = -\alpha\phi X + \beta(X - \eta(X)\xi).$$

Let M be submanifold of an almost contact metric manifold \bar{M} with induced metric g and if ∇ and ∇^\perp are the induced connections on the tangent bundle TM and the normal bundle $T^\perp M$ of M , respectively then Gauss and Weingarten formulae are given by

$$(2.5) \quad \bar{\nabla}_X Y = \nabla_X Y + h(X, Y)$$

$$(2.6) \quad \bar{\nabla}_X N = -A_N X + \nabla_X^\perp N,$$

for each $X, Y \in TM$ and $N \in T^\perp M$, where h and A_N are the second fundamental form and the shape operator (corresponding to the normal vector field N) respectively for the immersion of M into \bar{M} . They are related as [17]

$$(2.7) \quad g(h(X, Y), N) = g(A_N X, Y),$$

where g denotes the Riemannian metric on \bar{M} as well as induced on M .

For any $X \in TM$, we write

$$(2.8) \quad \phi X = PX + FX,$$

where PX is the tangential component and FX is the normal component of ϕX .

Similarly, for any $N \in T^\perp M$, we write

$$(2.9) \quad \phi N = BN + CN,$$

where BN is the tangential component and CN is the normal component of ϕN . The covariant derivatives of the tensor fields P and F are defined as

$$(2.10) \quad (\nabla_X P)Y = \nabla_X PY - P\nabla_X Y,$$

$$(2.11) \quad (\bar{\nabla}_X F)Y = \nabla_X^\perp FY - F\nabla_X Y$$

for all $X, Y \in TM$. The canonical structures P and F on a submanifold M are said to be *parallel* if $\nabla P = 0$ and $\bar{\nabla} F = 0$, respectively.

We shall always consider ξ to be tangent to M . The submanifold M is said to be *invariant* if F is identically zero, that is, $\phi X \in TM$ for any $X \in TM$. On the other hand M is said to be *anti-invariant* if P is identically zero, that is, $\phi X \in T^\perp M$, for any $X \in TM$.

For each non zero vector X tangent to M at x , such that X is not proportional to ξ , we denote by $\theta(X)$, the angle between ϕX and PX .

M is said to be *slant* [5] if the angle $\theta(X)$ is constant for all $X \in TM - \{\xi\}$ and $x \in M$. The angle θ is called *slant angle* or *Wirtinger angle*. Obviously if $\theta = 0$, M is invariant and if $\theta = \pi/2$, M is an anti-invariant submanifold. If the slant angle of M is different from 0 and $\pi/2$ then it is called *proper slant*.

A characterization of slant submanifolds is given by the following

Theorem 2.1 [5]. *Let M be a submanifold of an almost contact metric manifold \bar{M} , such that $\xi \in TM$. Then M is slant if and only if there exists a constant $\lambda \in [0, 1]$ such that*

$$(2.12) \quad P^2 = \lambda(-I + \eta \otimes \xi).$$

Furthermore, if θ is slant angle, then $\lambda = \cos^2 \theta$.

The following relations are straightforward consequences of equation (2.12):

$$(2.13) \quad g(PX, PY) = \cos^2 \theta [g(X, Y) - \eta(X)\eta(Y)]$$

$$(2.14) \quad g(FX, FY) = \sin^2 \theta [g(X, Y) - \eta(X)\eta(Y)]$$

for any X, Y tangent to M .

The study of semi-slant submanifolds of almost Hermitian manifolds was introduced by N. Papaghuic [14], which were latter extended to almost contact metric manifold by J.L. Cabrerizo et.al [4]. We say M is a *semi-slant submanifold* of \bar{M} if there exist an orthogonal direct decomposition of TM as

$$TM = D_1 \oplus D_2 \oplus \{\xi\}$$

where D_1 is an invariant distribution i.e., $\phi(D_1) = D_1$ and D_2 is slant with slant angle $\theta \neq 0$. The orthogonal complement of FD_2 in the normal bundle $T^\perp M$, is an invariant subbundle of $T^\perp M$ and is denoted by μ . Thus, we have

$$T^\perp M = FD_2 \oplus \mu.$$

Similarly, we say that M is *anti-slant submanifold* of \bar{M} if D_1 is an anti-invariant distribution of M i.e., $\phi D_1 \subseteq T^\perp M$ and D_2 is slant with slant angle $\theta \neq 0$.

3 Warped and doubly warped product submanifolds

Let (N_1, g_1) and (N_2, g_2) be two Riemannian manifolds and f , a positive differentiable function on N_1 . The warped product of N_1 and N_2 is the Riemannian manifold $N_1 \times_f N_2 = (N_1 \times N_2, g)$, where

$$(3.1) \quad g = g_1 + f^2 g_2.$$

A warped product manifold $N_1 \times_f N_2$ is said to be *trivial* if the warping function f is constant. We recall the following general formula on a warped product [2].

$$(3.2) \quad \nabla_X V = \nabla_V X = (X \ln f)V,$$

where X is tangent to N_1 and V is tangent to N_2 .

Let $M = N_1 \times_f N_2$ be a warped product manifold, this means that N_1 is totally geodesic and N_2 is totally umbilical submanifold of M , respectively.

Doubly warped product manifolds were introduced as a generalization of warped product manifolds by B. Ünal [16]. A *doubly warped product manifold* of N_1 and N_2 , denoted as $_{f_2}N_1 \times_{f_1}N_2$ is endowed with a metric g defined as

$$(3.3) \quad g = f_2^2 g_1 + f_1^2 g_2$$

where f_1 and f_2 are positive differentiable functions on N_1 and N_2 respectively.

In this case formula (3.2) is generalized as

$$(3.4) \quad \nabla_X V = (X \ln f_1)V + (V \ln f_2)X$$

for each $X \in TN_1$ and $V \in TN_2$ [12].

If neither f_1 nor f_2 is constant we have a non trivial doubly warped product $M = _{f_2}N_1 \times_{f_1}N_2$. Obviously in this case both N_1 and N_2 are totally umbilical submanifolds of M .

Theorem 3.1. *There do not exist proper doubly warped product submanifolds $M = {}_f N_1 \times {}_f N_2$ of a trans-Sasakian manifold \bar{M} where N_1 and N_2 are any Riemannian submanifolds of \bar{M} .*

Proof. For any $X \in TN_1$ and $Z \in TN_2$ then by (3.4) we have

$$\nabla_Z X = \nabla_X Z = (X \ln f_1)Z + (Z \ln f_2)X.$$

If $\xi \in TN_1$ then above equation gives

$$(3.5) \quad \nabla_Z \xi = (\xi \ln f_1)Z + (Z \ln f_2)\xi.$$

On the other hand, using (2.4) and the fact that ξ is tangent to N_1 we have

$$\bar{\nabla}_Z \xi = -\alpha\phi Z + \beta Z.$$

By (2.5) and (2.8), we get

$$\nabla_Z \xi + h(Z, \xi) = -\alpha PZ + \beta Z - \alpha FZ.$$

Using (3.5) and then comparing the tangential and normal components we obtain

$$(3.6) \quad (\xi \ln f_1)Z + (Z \ln f_2)\xi = -\alpha PZ + \beta Z$$

and

$$h(Z, \xi) = -\alpha FZ.$$

Taking product with Z in (3.6) and using the fact that ξ , Z and PZ are orthogonal vector fields then

$$\xi \ln f_1 = \beta, \quad Z \ln f_2 = 0.$$

This shows that f_2 is constant.

Similarly, if the structure vector field ξ is tangent to N_2 and for any $X \in TN_1$ we obtain

$$\xi \ln f_2 = \beta, \quad X \ln f_1 = 0,$$

showing that f_1 is constant. This completes the proof. \square

The following corollary is an immediate consequence of the above theorem:

Corollary 3.1. *There do not exist warped product submanifolds $M = N_1 \times_f N_2$ of a trans-Sasakian manifold \bar{M} such that $\xi \in TN_2$, where N_1 and N_2 are any Riemannian submanifolds of \bar{M} .*

Thus, the only remaining case to study of warped product submanifolds $N_1 \times_f N_2$ of trans-Sasakian manifolds is that the structure vector field ξ tangential to the first factor i.e., $\xi \in TN_1$. In this case, first we obtain some useful formulae for later use.

Lemma 3.1. *Let $M = N_1 \times_f N_2$ be warped product submanifolds of a trans-Sasakian manifold \bar{M} such that ξ is tangent to N_1 , where N_1 and N_2 are any Riemannian submanifolds of \bar{M} . Then*

$$(i) \quad \xi \ln f = \beta,$$

$$(ii) \quad A_{FZ}X = -Bh(X, Z),$$

$$(iii) \quad g(h(X, Y), FZ) = g(h(X, Z), FY),$$

$$(iv) \quad g(h(X, Z), FW) = g(h(X, W), FZ)$$

for any $X, Y \in TN_1$ and $Z, W \in TN_2$ where β is a smooth function on \bar{M} .

Proof. First part follows by Theorem 3.1. Now, for any $X \in TN_1$ and $Z \in TN_2$ we have

$$(\bar{\nabla}_X \phi)Z = \bar{\nabla}_X \phi Z - \phi \bar{\nabla}_X Z.$$

Using (2.3) and the fact that $\xi \in TN_1$, left hand side of the above equation is zero by orthogonality of two distributions, then

$$\bar{\nabla}_X \phi Z = \phi \bar{\nabla}_X Z.$$

By (2.5), (2.6), (2.8) and (2.9) we obtain

$$\nabla_X PZ + h(X, PZ) - A_{FZ}X + \nabla_X^\perp FZ = P\nabla_X Z + F\nabla_X Z + Bh(X, Z) + Ch(X, Z).$$

Equating the tangential and normal components and using (3.2), we get

$$(3.7) \quad A_{FZ}X = -Bh(X, Z)$$

and

$$(3.8) \quad \nabla_X^\perp FZ = (X \ln f)FZ + Ch(X, Z) - h(X, PZ).$$

Equation (3.7) follows part (ii). Parts (iii) and (iv) follow by taking the product in (ii) with $Y \in TN_1$ and $W \in TN_2$, respectively. \square

In the following section we shall investigate warped product semi-slant submanifolds of trans-Sasakian manifolds.

4 Warped product semi-slant submanifolds

We have seen that the warped products of the type $N_1 \times_f N_2$ of trans-Sasakian manifolds do not exist if the structure vector field ξ is tangent to N_2 . Thus, in this section we study warped product semi-slant submanifolds $N_1 \times_f N_2$ of trans-Sasakian manifolds only when $\xi \in TN_1$. If the manifolds N_θ and N_T (resp. N_\perp) are slant and invariant (resp. anti-invariant) submanifolds of a trans-Sasakian manifold \bar{M} , then their warped product semi-slant submanifolds may given by one of the following forms:

$$(i) \quad N_T \times_f N_\theta, \quad (ii) \quad N_\perp \times_f N_\theta,$$

$$(iii) \quad N_\theta \times_f N_T, \quad (iv) \quad N_\theta \times_f N_\perp.$$

For the warped products of the type (i), we have

Theorem 4.1. *Let $M = N_T \times_f N_\theta$ be warped product semi-slant submanifolds of a trans-Sasakian manifold \bar{M} such that ξ is tangent to N_T . Then $(\bar{\nabla}_X F)Z$ lies in the invariant normal subbundle for all $X \in TN_T$ and $Z \in TN_\theta$ where N_T and N_θ are invariant and proper slant submanifolds of \bar{M} .*

Proof. For any $X \in TN_T$ and $Z \in TN_\theta$ we have

$$g(\phi \bar{\nabla}_X Z, \phi Z) = g(\bar{\nabla}_X Z, Z).$$

Then from (3.2), we obtain

$$(4.1) \quad g(\phi \bar{\nabla}_X Z, \phi Z) = (X \ln f) \|Z\|^2.$$

On the other hand we have

$$(\bar{\nabla}_X \phi)Z = \bar{\nabla}_X \phi Z - \phi \bar{\nabla}_X Z,$$

for any $X \in TN_T$ and $Z \in TN_\theta$. Using (2.3) and the fact that ξ is in TN_T , left hand side of the above equation is zero, then

$$\phi \bar{\nabla}_X Z = \bar{\nabla}_X \phi Z.$$

Taking the product with ϕZ and then using (2.8), we get

$$g(\phi \bar{\nabla}_X Z, \phi Z) = g(\bar{\nabla}_X (PZ + FZ), PZ + FZ).$$

Then on applying (2.5) and (2.6) we obtain

$$\begin{aligned} g(\phi \bar{\nabla}_X Z, \phi Z) &= g(\nabla_X PZ, PZ) + g(h(X, PZ), FZ) \\ &\quad - g(A_{FZ} X, PZ) + g(\nabla_X^\perp FZ, FZ). \end{aligned}$$

Thus from (2.7) and (3.2) we have

$$g(\phi \bar{\nabla}_X Z, \phi Z) = (X \ln f)g(PZ, PZ) + g((\bar{\nabla}_X F)Z, FZ) + (X \ln f)g(FZ, FZ).$$

On using (2.13) and (2.14), we get

$$g(\phi \bar{\nabla}_X Z, \phi Z) = (X \ln f) \cos^2 \theta \|Z\|^2 + g((\bar{\nabla}_X F)Z, FZ) + (X \ln f) \sin^2 \theta \|Z\|^2,$$

or

$$(4.2) \quad g(\phi \bar{\nabla}_X Z, \phi Z) = (X \ln f) \|Z\|^2 + g((\bar{\nabla}_X F)Z, FZ).$$

By equations (4.1) and (4.2), it follows that

$$(4.3) \quad g((\bar{\nabla}_X F)Z, FZ) = 0.$$

for any $X \in TN_T$ and $Z \in TN_\theta$. Since N_θ is a proper slant submanifold of \bar{M} , then (4.3) implies $(\bar{\nabla}_X F)Z \in \mu$. The proof is complete. \square

For the warped product of the type $N_\perp \times_f N_\theta$ of a trans-Sasakian manifold \bar{M} such that $\xi \in TN_\perp$, we have the following theorem

Theorem 4.2. *Let $M = N_\perp \times_f N_\theta$ be warped product semi-slant submanifolds of a trans-Sasakian manifold \bar{M} such that ξ is tangent to N_\perp . Then*

$$(4.4) \quad Z \ln f = \beta \eta(Z)$$

for any $Z \in TN_{\perp}$ where β is a smooth function on \bar{M} and N_{\perp} and N_{θ} are anti-invariant and proper slant submanifolds of \bar{M} , respectively.

Proof. For any $X \in TN_{\theta}$ and $Z \in TN_{\perp}$ we have

$$(\bar{\nabla}_X \phi)Z = \bar{\nabla}_X \phi Z - \phi \bar{\nabla}_X Z.$$

On using (2.5), (2.6), (2.8), (2.9) and the structure equation of trans-Sasakian and the fact that $\xi \in TN_{\perp}$, we obtain

$$\begin{aligned} -\eta(Z)\alpha X - \beta\eta(Z)PX - \beta\eta(Z)FX &= -A_{FZ}X + \nabla_X^{\perp}FZ - P\nabla_X Z \\ -F\nabla_X Z - Bh(X, Z) - Ch(X, Z). \end{aligned}$$

Equating the tangential components and using (3.2), we get

$$(4.5) \quad \eta(Z)\alpha X + \beta\eta(Z)PX = A_{FZ}X + (Z \ln f)PX + Bh(X, Z).$$

Taking the product with PX in (4.5) and using the fact that X and PX are mutually orthogonal vector fields, then

$$\beta\eta(Z)g(PX, PX) = g(A_{FZ}X, PX) + (Z \ln f)g(PX, PX) + g(Bh(X, Z), PX).$$

Thus from (2.7) and (2.13) we get

$$(4.6) \quad \{\beta\eta(Z) - (Z \ln f)\} \cos^2 \theta \|X\|^2 = g(h(X, PX), FZ) - g(h(X, Z), FPX).$$

As N_{θ} is proper slant, interchanging X by PX in (4.6) and taking account of equation (2.12), we deduce that

$$(4.7) \quad \{\beta\eta(Z) - (Z \ln f)\} \cos^2 \theta \|X\|^2 = -g(h(X, PX), FZ) + g(h(PX, Z), FX).$$

On adding (4.6) and (4.7), we obtain

$$(4.8) \quad 2\{\beta\eta(Z) - (Z \ln f)\} \cos^2 \theta \|X\|^2 = g(h(PX, Z), FX) - g(h(X, Z), FPX).$$

Thus by Lemma 3.1 (iv), the right hand side of the above equation is zero then we have

$$\{\beta\eta(Z) - (Z \ln f)\} \cos^2 \theta \|X\|^2 = 0.$$

Since N_{θ} is proper slant and X is non-null, then $Z \ln f = \beta\eta(Z)$. Hence the theorem is proved. \square

Now, the case (iii) is dealt with the following

Proposition 4.1. *Let \bar{M} be a $(2n + 1)$ -dimensional trans-Sasakian manifold and $M = N_{\theta} \times_f N_T$ be warped product semi-slant submanifolds of \bar{M} such that ξ is tangent to N_{θ} . Then*

$$(4.9) \quad g((\bar{\nabla}_X F)Z, FZ) = \sec^2 \theta g((\bar{\nabla}_X F)PZ, FPZ)$$

for any $X \in TN_T$ and $Z \in TN_{\theta}$ where N_T and N_{θ} are invariant and proper slant submanifolds of \bar{M} , respectively.

Proof. Assume $M = N_\theta \times_f N_T$ be warped product semi-slant submanifolds of a trans-Sasakian manifold \bar{M} such that ξ is tangent to N_θ . Then for any $X \in TN_T$ and $Z \in TN_\theta$ we have

$$(\bar{\nabla}_X \phi)Z = \bar{\nabla}_X \phi Z - \phi \bar{\nabla}_X Z.$$

Since $\xi \in TN_\theta$ then from (2.3), (2.5), (2.6), (2.8) and (2.9), we get

$$\begin{aligned} -\eta(Z)\alpha X - \beta\eta(Z)\phi X &= \nabla_X PZ + h(X, PZ) - A_{FZ}X + \nabla_X^\perp FZ \\ &\quad - P\nabla_X Z - F\nabla_X Z - Bh(X, Z) - Ch(X, Z). \end{aligned}$$

On comparing the tangential and normal parts we have

$$(4.10) \quad -\eta(Z)\alpha X - \beta\eta(Z)\phi X = \nabla_X PZ - A_{FZ}X - P\nabla_X Z - Bh(X, Z)$$

and

$$(4.11) \quad (\bar{\nabla}_X F)Z = Ch(X, Z) - h(X, PZ).$$

Taking the product with FZ in (4.11) we have

$$\begin{aligned} g((\bar{\nabla}_X F)Z, FZ) &= g(Ch(X, Z), FZ) - g(h(X, PZ), FZ) = \\ &= g(\phi h(X, Z), \phi Z) - g(Bh(X, Z), PZ) - g(h(X, PZ), \phi Z). \end{aligned}$$

That is,

$$(4.12) \quad g((\bar{\nabla}_X F)Z, FZ) = -g(Bh(X, Z), PZ) + g(Bh(X, PZ), Z).$$

As $\theta \neq \frac{\pi}{2}$, then substituting Z by PZ in (4.12) and using (2.12) we obtain

$$g((\bar{\nabla}_X F)PZ, FPZ) = \cos^2 \theta \{-g(Bh(X, Z), PZ) + g(Bh(X, PZ), Z)\}.$$

Using (4.12), we get

$$g((\bar{\nabla}_X F)PZ, FPZ) = \cos^2 \theta g((\bar{\nabla}_X F)Z, FZ).$$

This proves our assertion. \square

The case (iv) is dealt in the following Theorem.

Theorem 4.3. *Let $M = N_T \times_f N_\perp$ be warped product submanifold of a trans-Sasakian manifold \bar{M} such that N_T an invariant submanifold tangent to ξ and N_\perp is an anti-invariant submanifold of \bar{M} . Then $(\bar{\nabla}_X F)Z$ lies in the invariant normal subbundle for each $X \in TN_T$ and $Z \in TN_\perp$.*

Proof. As $M = N_T \times_f N_\perp$ be warped product submanifold with ξ is tangent to N_T , then for any $X \in TN_T$ and $Z \in TN_\perp$ we have

$$(\bar{\nabla}_X \phi)Z = \bar{\nabla}_X \phi Z - \phi \bar{\nabla}_X Z.$$

On using (2.3) and the fact that ξ tangential to N_T the left hand side of the above equation is zero. Thus, we have

$$\bar{\nabla}_X \phi Z = \phi \bar{\nabla}_X Z.$$

Then from (2.5) and (2.6) we obtain

$$-A_{FZ}X + \nabla_X^\perp FZ = \phi(\nabla_X Z + h(X, Z)).$$

Which on using (2.8) and (2.9) yields

$$-A_{FZ}X + \nabla_X^\perp FZ = P\nabla_X Z + F\nabla_X Z + Bh(X, Z) + Ch(X, Z).$$

From the normal components of the above equation and formula (3.2) gives

$$(4.13) \quad \nabla_X^\perp FZ = (X \ln f)FZ + Ch(X, Z).$$

Taking the product in (4.13) with FW_1 for any $W_1 \in TN_\perp$, we get

$$g(\nabla_X^\perp FZ, FW_1) = (X \ln f)g(FZ, FW_1) + g(Ch(X, Z), FW_1)$$

or,

$$g(\nabla_X^\perp FZ, FW_1) = (X \ln f)g(\phi Z, \phi W_1) + g(\phi h(X, Z), \phi W_1).$$

Then from (2.2) we have

$$(4.14) \quad g(\nabla_X^\perp FZ, FW_1) = (X \ln f)g(Z, W_1).$$

On the other hand for any $X \in TN_T$ and $Z \in TN_\perp$ we have

$$(\bar{\nabla}_X F)Z = \nabla_X^\perp FZ - F\nabla_X Z.$$

Taking the product with FW_1 , for any $W_1 \in TN_\perp$ and using (3.2), we get

$$(4.15) \quad g((\bar{\nabla}_X F)Z, FW_1) = g(\nabla_X^\perp FZ, FW_1) - (X \ln f)g(Z, W_1).$$

Equations (4.14) and (4.15), it follows that

$$(4.16) \quad g((\bar{\nabla}_X F)Z, FW_1) = 0,$$

for any $X \in TN$ and $Z, W_1 \in TN_\perp$. Now, if $W_2 \in TN_T$ then using the formula (2.11), we get

$$g((\bar{\nabla}_X F)Z, \phi W_2) = g(\nabla_X^\perp FZ, \phi W_2) - g(F\nabla_X Z, \phi W_2).$$

As N_T is an invariant submanifold then $\phi W_2 \in TN_T$ for any $W_2 \in TN_T$, thus using the fact that the product of tangential component with normal is zero, we obtain that

$$(4.17) \quad g((\bar{\nabla}_X F)Z, \phi W_2) = 0,$$

for any $X, W_2 \in TN_T$ and $Z \in TN_\perp$. Thus from equations (4.16) and (4.17) it follows that $(\bar{\nabla}_X F)Z \in \mu$. This proves the theorem completely. \square

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Authors' addresses:

Siraj Uddin
 Institute of Mathematical Sciences, Faculty of Science,
 University of Malaya, 50603 Kuala Lumpur, Malaysia.
 E-mail: siraj.ch@gmail.com

Khalid Ali Khan
 School of Engineering & Logistics, Faculty of Technology,
 Charles Darwin University, NT-0909, Australia.
 E-mail: khalid.mathematics@gmail.com