The Curvature Theory of Generalized Connection in Osc^2M

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Abstract

In the paper are presented the explicit expressions for the components of the torsion and curvature of a generalized connection on the 2-osculator bundle of a real differentiable manifold; the corresponding Ricci identities for the generalized connection are also derived.

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1 Introduction

Let M be a C^{∞} , n-dimensional manifold and $E=(Osc^2M,\pi,M)$ its 2-osculator bundle. The K-osculator bundle was studied among others in [15], [16], [17], where the adapted basis is determined. As we here need more types of indices, the adapted basis of T(E) and $T^*(E)$ will be presented.

Some point $u \in E$ in the local charts (U, φ) and (U', φ') has coordinates (x^i, y^i, z^i) and $(x^{i'}, y^{i'}, z^{i'})$ respectively, $i = 1, 2, \ldots, n$. In $U \cap U'$ the allowable coordinate transformations are given by the equations

(1.1)
$$x^{i'} = x^{i'}(x) \quad rank \left| \frac{\partial x^{i'}}{\partial x^i} \right| = n$$

$$y^{i'} = \frac{\partial x^{i'}}{\partial x^j} y^j$$

$$z^{i'} = \frac{1}{2} \frac{\partial^2 x^{i'}}{\partial x^k \partial x^j} y^k y^j + \frac{\partial x^{i'}}{\partial x^j} z^j.$$

It can be shown, that the transformations of type (1.1) form a group. The adapted basis B of T(E) is

(1.2)
$$B = \{ \frac{\delta}{\delta x^i}, \frac{\delta}{\delta y^i}, \frac{\partial}{\partial z^i} \},$$

where

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(1.3)
$$\frac{\delta}{\delta x^{i}} = \frac{\partial}{\partial x^{i}} - (1)\mathcal{N}_{i}^{j} \frac{\partial}{\partial y^{j}} - (2)\mathcal{N}_{i}^{j} \frac{\partial}{\partial z^{j}}$$

(1.4)
$$\frac{\delta}{\delta y^i} = \frac{\partial}{\partial y^i} - (1)\mathcal{N}_i^j \frac{\partial}{\partial z^j}$$

Theorem 1.1. The element of B ((1.2)) with respect to (1.1) are transformed as tensors, i.e.

(1.5)
$$\frac{\delta}{\delta x^{i}} = \frac{\partial x^{i'}}{\partial x^{i}} \frac{\delta}{\delta x^{i'}}, \quad \frac{\delta}{\delta y^{i}} = \frac{\partial x^{i'}}{\partial x^{i}} \frac{\delta}{\delta y^{i'}}, \quad \frac{\partial}{\partial z^{i}} = \frac{\partial x^{i'}}{\partial x^{i}} \frac{\partial}{\partial z^{i'}}$$

if the nonlinear connections (1) $\mathcal N$ and (2) $\mathcal N$ are transformed in the following way:

(1.6)
$$(1)\mathcal{N}_{i'}^{j'} = (1)\mathcal{N}_{i}^{j} \frac{\partial x^{i}}{\partial x^{i'}} \frac{\partial x^{j'}}{\partial x^{j}} - \frac{\partial y^{j'}}{\partial x^{i}} \frac{\partial x^{i}}{\partial x^{i'}},$$

$$(1.7) (2)\mathcal{N}_{i'}^{j'} = (2)\mathcal{N}_{i}^{j} \frac{\partial x^{i}}{\partial x^{i'}} \frac{\partial x^{j'}}{\partial x^{j}} + (1)\mathcal{N}_{i}^{j} \frac{\partial y^{j'}}{\partial x^{j}} \frac{\partial x^{i}}{\partial x^{i'}} - \frac{\partial z^{j'}}{\partial x^{i}} \frac{\partial x^{i}}{\partial x^{i'}}.$$

The basis of $T^*(E)$ dual to B is

$$(1.8) B^* = \{dx^i, \delta y^i, \delta z^i\},$$

where

(1.9)
$$\delta y^i = dy^i + (1)\mathcal{M}_i^i dx^j$$

(1.10)
$$\delta z^{i} = dz^{i} + (1)\mathcal{M}_{i}^{i}dy^{j} + (2)\mathcal{M}_{i}^{i}dx^{j}.$$

Theorem 1.2. The elements of B^* ((1.8)) with respect to (1.1) are transformed as

(1.11)
$$dx^{i'} = \frac{\partial x^{i'}}{\partial x^i} dx^i, \ \delta y^{i'} = \frac{\partial x^{i'}}{\partial x^i} \delta y^i, \ \delta z^{i'} = \frac{\partial x^{i'}}{\partial x^i} \delta z^i$$

if for the nonlinear connections (1) \mathcal{M} and (2) \mathcal{M} the following equations are valid

$$(1.12) (1)\mathcal{M}_i^i = (1)\mathcal{N}_i^i$$

(1.13)
$$(2)\mathcal{M}_{i}^{i} = (2)\mathcal{N}_{i}^{i} + (1)\mathcal{N}_{m}^{i}(1)\mathcal{N}_{m}^{m}.$$

If we denote as T_H , T_{V_1} , T_{V_2} the subspaces of T(E) spanned by $\{\frac{\delta}{\delta x^i}\}$, $\{\frac{\delta}{\delta y^i}\}$, $\{\frac{\partial}{\partial z^i}\}$ and as T_H^* , $T_{V_1}^*$, $T_{V_2}^*$ the subspaces of $T^*(E)$ spanned by $\{dx^i\}$, $\{\delta y^i\}$, $\{\delta z^i\}$ respectively, then

$$T(E) = T_H \oplus T_{V_1} \oplus T_{V_2}, \qquad T^*(E) = T_H^* \oplus T_{V_1}^* \oplus T_{V_2}^*.$$

For the further examinations it is useful to introduce different kinds of indices. Indices $i, j, h, k, l = \overline{1, n}$ will be used in T_H and T_H^* $a, b, c, d, e, f = \overline{n+1, \dots, 2n}$ in T_{V_1} and $T_{V_1}^*$, $p,q,r,s,t=\overline{2n+1,\ldots,3n}$ in T_{V_2} and $T_{V_2}^*$. The Greek letters as indices will take values from 1 to 3n. Using these notations the adapted basis Band B^* given by (1.2) and (1.8) have the form:

(1.14)
$$B = \{ \frac{\delta}{\delta x^i}, \frac{\delta}{\delta y^a}, \frac{\partial}{\partial z^p} \} = \{ \delta_i, \delta_a, \partial_p \} = \{ \delta_\alpha \},$$

(1.15)
$$B^* = \{dx^j, \delta y^b, \delta z^p\} = \{\delta^\beta\},\,$$

where from (1.3), (1.4), (1.9) and (1.10) we get

(a)
$$\frac{\delta}{\delta x^i} = \frac{\partial}{\partial x^i} = \frac{\partial}{\partial x^i} - (1)\mathcal{N}_i^b \frac{\partial}{\partial y^b} - (2)\mathcal{N}_i^q \frac{\partial}{\partial z^q}$$

$$(1.16) (b) \frac{\overline{\delta y^a}}{\delta y^a} = \frac{\partial y^a}{\partial y^a} - (1)\mathcal{N}_a \frac{\partial z^a}{\partial z^a}$$

$$(2.16) (c) \delta y^a = dy^a + (1)\mathcal{N}_a dx^i$$

$$\begin{array}{lll} \text{(a)} & \frac{\delta}{\delta x^i} & = & \frac{\partial}{\partial x^i} = \frac{\partial}{\partial x^i} - (1)\mathcal{N}_i^b \frac{\partial}{\partial y^b} - (2)\mathcal{N}_i^q \frac{\partial}{\partial z^q} \\ \text{(b)} & \frac{\delta}{\delta y^a} & = & \frac{\partial}{\partial y^a} - (1)\mathcal{N}_a^q \frac{\partial}{\partial z^q} \\ \text{(c)} & \delta y^a & = & dy^a + (1)\mathcal{N}_i^a dx^i \\ \text{(d)} & \delta z^q & = & dz^q + (1)\mathcal{N}_a^q dy^a + ((2)\mathcal{N}_j^q + (1)\mathcal{N}_j^r (1)\mathcal{N}_r^q) dx^j = \\ & = & dz^q + (1)\mathcal{N}_a^q \delta y^a + (2)\mathcal{N}_j^q dx^j \,. \end{array}$$

$$(1)\mathcal{N}_{i}^{j} = (1)\mathcal{N}_{i}^{b} = (1)\mathcal{N}_{a}^{q}, (2)\mathcal{N}_{i}^{q} = (2)\mathcal{N}_{i}^{j}$$

if i = a(modn) and j = b = q(modn).

Some vector field $X \in T(E)$ and some 1-form $w \in T^*(E)$ expressed in the bases B and B^* have the form:

(1.17)
$$X = X^{i} \frac{\delta}{\delta x^{i}} + X^{a} \frac{\delta}{\delta y^{a}} + X^{p} \frac{\partial}{\partial z^{p}} = X^{\alpha} \delta_{\alpha}$$
$$w = w_{j} dx^{j} + w_{b} \delta y^{b} + w_{q} \delta z^{q} = w_{\beta} \delta^{\beta}.$$

With respect to (1.1) the coordinates of X and w transform in the following way:

$$\begin{array}{lll} X^{i'} & = & X^i \frac{\partial x^{i'}}{\partial x^{i'}}, \ X^{a'} = X^a \frac{\partial y^{a'}}{\partial y^a}, \ X^{p'} = X^p \frac{\partial z^{p'}}{\partial z^p}, \\ w_{j'} & = & w_j \frac{\partial x^j}{\partial x^{j'}}, \ w_{b'} = w_b \frac{\partial y^b}{\partial y^{b'}}, \ w_{q'} = w_q \frac{\partial z^q}{\partial z^{q'}}, \end{array}$$

because if i = a = p(modn) we have

$$\frac{\partial x^{i'}}{\partial x^i} = \frac{\partial y^{a'}}{\partial y^a} = \frac{\partial z^{p'}}{\partial z^p}.$$

The generalized connection on T(E)2

Let $\nabla: T(E) \times T(E) \to T(E)$ be a linear connection such that $\nabla: (X,Y) \to T(E)$ $\nabla_X Y \in T(E), \forall X, Y \in T(E).$

Definition 2.1. The generalized connection on T(E) is a linear connection ∇ determined by:

(2.1)
$$\begin{array}{rcl} (\mathbf{a}) & \nabla_{\delta_{i}} \delta_{\beta} & = & F_{\beta i}^{\kappa} \delta_{\kappa}, \\ (\mathbf{b}) & \nabla_{\delta_{a}} \delta_{\beta} & = & C_{\beta a}^{\kappa} \delta_{\kappa}, \\ (\mathbf{c}) & \nabla_{\partial_{p}} \delta_{\beta} & = & L_{\beta p}^{\kappa} \delta_{\kappa}, \end{array}$$

(c)
$$\nabla_{\partial_p} \delta_{\beta} = L_{\beta p}^{\kappa} \delta_{\kappa}$$

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where $\beta = j$ or $\beta = b$ or $\beta = q$ and

(2.2)
$$T_{\cdots}^{\kappa} \delta_{\kappa} = T_{\cdots}^{\kappa} \delta_{k} + T_{\cdots}^{c} \partial_{c} + T_{\cdots}^{r} \partial_{r}.$$

We shall use the abbreviated form of (2.1):

(2.3)
$$\nabla_{\delta_{\alpha}} \delta_{\beta} = \Gamma_{\beta \alpha}^{\kappa} \delta_{\kappa}.$$

From (2.1) and (2.3) follows:

If
$$\alpha = i$$
, then $\Gamma = F$; if $\alpha = a$, then $\Gamma = C$; if $\alpha = p$, then $\Gamma = L$.

Proposition 2.1. If X is the vector field ((1.17)) defined on E, then the following equations are valid:

(2.4)
$$\begin{aligned} \nabla_{\delta_{i}}X &= X_{|i}^{\alpha}\delta_{\alpha} &, & X_{|i}^{\alpha} &= \delta_{i}X^{\alpha} + F_{\beta i}^{\alpha}X^{\beta} \\ \nabla_{\partial_{a}}X &= X^{\alpha}|_{a}\delta_{\alpha} &, & X^{\alpha}|_{a} &= \partial_{a}X^{\alpha} + C_{\beta a}^{\alpha}X^{\beta} \\ \nabla_{\partial_{p}}X &= X^{\alpha}|_{p}\delta_{\alpha} &, & X^{\alpha}|_{p} &= \partial_{p}X^{\alpha} + L_{\beta p}^{\alpha}X^{\beta}, \end{aligned}$$

where

(2.5)
$$\Gamma_{\dot{\beta}} X^{\beta} = \Gamma_{\dot{\beta}} X^{\dot{\beta}} + \Gamma_{\dot{b}} X^{\dot{b}} + \Gamma_{\dot{q}} X^{\dot{q}}, \ (\Gamma = F \text{ or } \Gamma = C \text{ or } \Gamma = L)$$

Theorem 2.1. If X and Y are vector fields in TE expressed in basis B, ∇ the generalized connection defined by (2.1), then

(2.6)
$$\nabla_Y X = (X^{\alpha}_{|\beta}) Y^{\beta} \delta_{\alpha},$$

where

$$(2.7) \qquad \qquad \cdots_{|\beta} Y^{\beta} = \cdots_{|j} Y^{j} + \cdots_{|b} Y^{b} + \cdots_{|q} Y^{q}.$$

Theorem 2.2. All covariant derivatives $X_{|i}^{\alpha}$, $X^{\alpha}|_a$, $X^{\alpha}|_p$ ($\alpha = j$, or $\alpha = b$, or $\alpha = p$) from (2.4) are transformed as tensors with respect to (1.1) if all connection coefficients from (2.1) are transformed as tensors, except the following which have the form:

$$(2.8) F_{ji}^{k} = F_{j'i'}^{k'} \frac{\partial x^{i'}}{\partial x^{i}} \frac{\partial x^{k}}{\partial x^{k'}} \frac{\partial x^{j'}}{\partial x^{j}} + \frac{\partial^{2} x^{k'}}{\partial x^{i} \partial x^{j}} \frac{\partial x^{k}}{\partial x^{k'}}$$

$$(2.9) F_{b'i}^{c} = F_{b'i'}^{c'} \frac{\partial x^{i'}}{\partial x^{i}} \frac{\partial y^{b'}}{\partial y^{b}} \frac{\partial y^{c}}{\partial y^{c'}} + \frac{\partial^{2} y^{c'}}{\partial x^{i} \partial y^{b}} \frac{\partial z^{r}}{\partial y^{c'}}$$

$$(2.10) F_{q i}^{r} = F_{q' i'}^{r'} \frac{\partial x^{i'}}{\partial x^{i}} \frac{\partial z^{q'}}{\partial z^{q}} \frac{\partial z^{r}}{\partial z^{r'}} + \frac{\partial^{2} z^{r'}}{\partial x^{i} \partial z^{q}} \frac{\partial z^{r}}{\partial z^{r'}}$$

Theorem 2.3. The torsion tensor T for the generalized connection ∇ has the form:

$$(2.11) T(X,Y) = \nabla_X Y - \nabla_Y X - [X,Y] = T_{\alpha\beta}^{\kappa} Y^{\alpha} X^{\beta} \delta_{\kappa},$$

where

$$(2.12) T_{\alpha\beta}^{\kappa} = \Gamma_{\alpha\beta}^{\kappa} - \Gamma_{\beta\alpha}^{\kappa}$$

except the following components:

$$(2.13) \begin{array}{rcl} T_{j\,i}^{\,c} &=& F_{j\,i}^{\,\,c} - F_{i\,j}^{\,\,c} + K_{j\,i}^{\,\,c} \\ T_{j\,b}^{\,\,c} &=& C_{j\,b}^{\,\,c} - F_{b\,j}^{\,\,c} + K_{j\,b}^{\,\,c} = - T_{b\,j}^{\,\,c} \\ T_{j\,i}^{\,\,r} &=& F_{j\,i}^{\,\,r} - F_{i\,j}^{\,\,r} + K_{j\,i}^{\,\,r} \\ T_{j\,b}^{\,\,r} &=& C_{j\,b}^{\,\,r} - F_{b\,j}^{\,\,r} + K_{j\,b}^{\,\,r} = - T_{b\,j}^{\,\,r} \\ T_{j\,q}^{\,\,r} &=& L_{j\,q}^{\,\,r} - F_{q\,j}^{\,\,r} + K_{j\,q}^{\,\,r} = - T_{q\,j}^{\,\,r} \\ T_{b\,a}^{\,\,r} &=& C_{b\,a}^{\,\,r} - C_{a\,b}^{\,\,r} + K_{a\,b}^{\,\,r} \end{array}$$

where

$$(2.14) \begin{array}{rcl} K_{i\,j}^{\,\,c} &=& \delta_{j}(1)\mathcal{N}_{i}^{\,c} - \delta_{i}(1)\mathcal{N}_{j}^{\,c}, \\ K_{i\,j}^{\,\,r} &=& \delta_{j}(2)\mathcal{N}_{i}^{\,r} - \delta_{i}(2)\mathcal{N}_{j}^{\,r} + (1)\mathcal{N}_{c}^{\,r}K_{i\,j}^{\,\,c}, \\ K_{i\,b}^{\,\,c} &=& \delta_{b}(1)\mathcal{N}_{i}^{\,c}, \\ K_{i\,b}^{\,\,r} &=& \delta_{b}(2)\mathcal{N}_{i}^{\,r} - \delta_{i}(1)\mathcal{N}_{b}^{\,r} + (1)\mathcal{N}_{c}^{\,r}K_{i\,b}^{\,\,c}, \\ K_{i\,q}^{\,\,r} &=& \partial_{q}(2)\mathcal{N}_{i}^{\,\,r}, \\ K_{a\,b}^{\,\,r} &=& \delta_{b}(1)\mathcal{N}_{a}^{\,r} - \delta_{a}(1)\mathcal{N}_{b}^{\,r}. \end{array}$$

Proof. By direct calculation we obtain

$$(2.15) [X,Y] = X^{\alpha}(\partial_{\alpha}Y^{\beta})\partial_{\beta} - Y^{\alpha}(\partial_{\alpha}X^{\beta})\partial_{\beta} + X^{\alpha}Y^{\beta}(\partial_{\alpha}\partial_{\beta} - \partial_{\beta}\partial_{\alpha}),$$

$$(2.16) X^{\alpha}Y^{\beta}(\partial_{\alpha}\partial_{\beta} - \partial_{\beta}\partial_{\alpha}) = X^{\alpha}Y^{\beta}K_{\alpha\beta}^{\kappa}\partial_{\kappa} =$$

$$= X^{i}Y^{j}(K_{ij}^{c}\delta_{c} + K_{ij}^{r}\partial_{r}) + (X^{i}Y^{b} - Y^{i}X^{b})(K_{ib}^{c}\delta_{c} + K_{ib}^{r}\partial_{r}) +$$

$$+ (X^{i}Y^{q} - Y^{i}X^{q})K_{iq}^{r}\partial_{r} + X^{a}Y^{b}K_{ab}^{r}\partial_{r}.$$

Substituting (2.15) and (2.16) into (2.11) we obtain (2.12) and (2.13).

3 The curvature theory of ∇

The curvature tensor for the generalized connection ∇ is defined as usual

(3.1)
$$R(X,Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,Y]} Z.$$

If we use the notations

$$X = X^{\alpha} \partial_{\alpha}, Y = Y^{\beta} \partial_{\beta}, Z = Z^{\gamma} \partial_{\gamma},$$

then we have

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$$(3.2) \begin{array}{c} \nabla_{X}\nabla_{Y}Z = \nabla_{X^{\alpha}\partial_{\alpha}}\nabla_{Y^{\beta}\partial_{\beta}}Z^{\gamma}\partial_{\gamma} = \\ \nabla_{X^{\alpha}\partial_{\alpha}}[Y^{\beta}(\partial_{\beta}Z^{\gamma})\partial_{\gamma} + Y^{\beta}Z^{\gamma}\Gamma^{\kappa}_{\gamma\beta}\partial_{\kappa}] = \\ X^{\alpha}(\partial_{\alpha}Y^{\beta})(\partial_{\beta}Z^{\gamma})\partial_{\gamma} + X^{\alpha}Y^{\beta}(\partial_{\alpha}\partial_{\beta}Z^{\gamma})\partial_{\gamma} + \\ X^{\alpha}Y^{\beta}(\partial_{\beta}Z^{\gamma})\Gamma^{\kappa}_{\gamma\alpha}\partial_{\kappa} + X^{\alpha}(\partial_{\alpha}Y^{\beta})Z^{\gamma}\Gamma^{\kappa}_{\gamma\beta}\partial_{\kappa} + \\ X^{\alpha}Y^{\beta}(\partial_{\alpha}Z^{\gamma})\Gamma^{\kappa}_{\gamma\beta}\partial_{\kappa} + X^{\alpha}Y^{\beta}Z^{\gamma}(\partial_{\alpha}\Gamma^{\kappa}_{\gamma\beta})\partial_{\kappa} + \\ X^{\alpha}Y^{\beta}Z^{\gamma}\Gamma^{\theta}_{\gamma\beta}\Gamma^{\kappa}_{\theta\alpha}\partial_{\kappa}. \end{array}$$

From (2.15) and (2.16) follows

(3.3)
$$\nabla_{[XY]}Z = X^{\alpha}(\partial_{\alpha}Y^{\beta})(\partial_{\beta}Z^{\gamma})\partial_{\gamma} + X^{\alpha}(\partial_{\alpha}Y^{\beta})Z^{\gamma}\Gamma_{\gamma\beta}^{\kappa}\partial_{\kappa} - Y^{\alpha}(\partial_{\alpha}X^{\beta})(\partial_{\beta}Z^{\gamma})\partial_{\gamma} - Y^{\alpha}(\partial_{\alpha}X^{\beta})Z^{\gamma}\Gamma_{\gamma\beta}^{\kappa}\partial_{\kappa} + X^{\alpha}Y^{\beta}[(\partial_{\alpha}\partial_{\beta} - \partial_{\beta}\partial_{\alpha})Z^{\gamma}]\partial_{\gamma} + X^{\alpha}Y^{\beta}Z^{\gamma}K_{\alpha\beta}^{\kappa}\Gamma_{\gamma\theta}^{\kappa}\partial_{\kappa}.$$

Substituting (3.2) and (3.3) into (3.1) we obtain

$$(3.4) \begin{array}{rcl} R(X,Y)Z & = & [K_{\gamma \ \beta \alpha}^{\ \kappa} X^{\alpha} Y^{\beta} - (K_{i \ j}^{\ c} C_{\gamma \ c}^{\ \kappa} + K_{i \ j}^{\ q} L_{\gamma \ q}^{\ \kappa}) X^{i} Y^{j} - \\ & & (K_{i \ b}^{\ c} C_{\gamma \ c}^{\ \kappa} + K_{i \ b}^{\ r} L_{\gamma \ r}^{\ \kappa}) (X^{i} Y^{b} - Y^{i} X^{b}) - \\ & & & K_{i \ q}^{\ r} L_{\gamma \ r}^{\ \kappa} (X^{i} Y^{q} - Y^{i} X^{q}) - K_{a \ b}^{\ r} L_{\gamma \ r}^{\ \kappa} X^{a} Y^{b}] Z^{\gamma} \partial_{\kappa}, \end{array}$$

where

$$(3.5)K_{\gamma\beta\alpha}^{\kappa} = (\partial_{\alpha}\Gamma_{\gamma\beta}^{\kappa} - \Gamma_{\gamma\alpha}^{\theta}\Gamma_{\theta\beta}^{\kappa}) - (\alpha, \beta).$$

As the indices α , β , γ , κ belong to one of the sets $\{i, j, k, l, \ldots\}$, $\{a, b, c, d, \ldots\}$, $\{p, q, r, s, t, \ldots\}$ (corresponding to T_H , T_{V_1} , T_{V_2} respectively), so on the TE we have $3^4 = 81$ types of curvature tensors. It is meaningless to introduce different letters as R, P, S for the curvature tensors as in Finsler geometry.

We shall denote

$$(3.6) R_{\gamma \beta \alpha}^{\kappa} = K_{\gamma \beta \alpha}^{\kappa}$$

for all (β, α) except when $(\beta, \alpha) = (j, i)$, $(\beta, \alpha) = (i, b)$, $(\beta, \alpha) = (i, q)$ and $(\beta, \alpha) = (b, a)$. In these cases we have

$$(3.7) \begin{array}{c} R_{\gamma \, ji}^{\, \kappa} = K_{\gamma \, ji}^{\, \kappa} - K_{i \, j}^{\, c} C_{\gamma \, c}^{\, \kappa} - K_{i \, j}^{\, q} L_{\gamma \, q}^{\, \kappa}, \\ R_{\gamma \, ib}^{\, \kappa} = K_{\gamma \, ib}^{\, \kappa} + K_{i \, b}^{\, c} C_{\gamma \, c}^{\, \kappa} + K_{i \, b}^{\, r} L_{\gamma \, r}^{\, \kappa} = -R_{\gamma \, bi}^{\, \kappa}, \\ R_{\gamma \, iq}^{\, \kappa} = K_{\gamma \, iq}^{\, \kappa} + K_{i \, q}^{\, p} L_{q \, p}^{\, \kappa} = -R_{\gamma \, qi}^{\, \kappa}, \\ R_{\gamma \, ba}^{\, \kappa} = K_{\gamma \, ba}^{\, \kappa} - K_{a \, b}^{\, r} L_{\gamma \, r}^{\, \kappa} = -R_{\gamma \, ab}^{\, \kappa}. \end{array}$$

As $R_{\gamma\beta\alpha}^{\kappa} = -R_{\gamma\alpha\beta}^{\kappa}$ we can write (3.4) in the form:

$$(3.8) \begin{array}{rcl} R(X,Y)Z & = & [\frac{1}{2}K_{\gamma}{}^{\kappa}{}_{\beta\alpha}(X^{\alpha}Y^{\beta}-Y^{\alpha}X^{\beta}) - \\ & \frac{1}{2}(K_{ij}{}^{c}C_{\gamma}{}^{c}+K_{ij}{}^{q}L_{\gamma}{}^{\kappa}{}_{q})(X^{i}Y^{j}-Y^{i}X^{j}) - \\ & \frac{1}{2}(K_{ib}{}^{c}C_{\gamma}{}^{\kappa}+K_{ij}{}^{r}L_{\gamma}{}^{\kappa}(X^{i}Y^{b}-Y^{i}X^{b}) + \\ & \frac{1}{2}(K_{ib}{}^{c}C_{\gamma}{}^{\kappa}+K_{ib}{}^{r}L_{\gamma}{}^{\kappa}(Y^{i}X^{b}-X^{i}Y^{b}) + \\ & \frac{1}{2}K_{iq}{}^{r}L_{\gamma}{}^{\kappa}(X^{i}Y^{q}-Y^{i}X^{q}) + \\ & \frac{1}{2}K_{iq}{}^{r}L_{\gamma}{}^{\kappa}(Y^{i}X^{q}-X^{i}Y^{q})] - \\ & \frac{1}{2}K_{ab}{}^{r}L_{\gamma}{}^{\kappa}(X^{a}Y^{b}-Y^{a}X^{b})Z^{\gamma}\delta_{\kappa} \end{array}$$

For $(\beta, \alpha) = (j, i)$ the sum of the first and the second line in (3.8) is equal to $\frac{1}{2}R_{\gamma ji}^{\kappa}(X^{i}Y^{j} - Y^{i}X^{j})$, for $(\beta, \alpha) = (b, i)$ the sum of the first and the third line in (3.8) is equal to $\frac{1}{2}R_{\gamma bi}^{\kappa}(X^{i}Y^{b} - Y^{i}X^{b})$ etc.

From (3.4)–(3.8) follows

Theorem 3.1. The curvature tensor of the generalized connection ∇ has the form

(3.9)
$$R(X,Y)Z = \frac{1}{2} R_{\gamma \beta \alpha}^{\kappa} (X^{\alpha} Y^{\beta} - Y^{\alpha} X^{\beta}) Z^{\gamma} \delta_{\kappa},$$

where the components of R are determined by (3.6) and (3.7).

Formula (3.9) is short and elegant, but the explicit form of curvature tensor is much longer, for instance if $(\beta, \alpha) = (b, i)$ from (3.5) and (3.7) we have:

$$\begin{array}{lcl} R_{\gamma\,bi}^{\,\,\kappa} &=& \delta_i C_{\gamma\,b}^{\,\,\kappa} - F_{\gamma\,i}^{\,\,\theta} C_{\theta\,b}^{\,\,\kappa} - \partial_b F_{\gamma\,i}^{\,\,\kappa} + C_{\gamma\,b}^{\,\,\theta} F_{\theta\,i}^{\,\,\kappa} - K_{i\,b}^{\,\,c} C_{\gamma\,c}^{\,\,\kappa} - K_{i\,b}^{\,\,r} L_{\gamma\,r}^{\,\,\kappa} = \\ && \delta_i C_{\gamma\,b}^{\,\,\kappa} - F_{\gamma\,i}^{\,\,k} C_{k\,b}^{\,\,\kappa} - F_{\gamma\,i}^{\,\,c} C_{c\,b}^{\,\,\kappa} - F_{\gamma\,i}^{\,\,r} C_{r\,b}^{\,\,\kappa} - \partial_b F_{\gamma\,i}^{\,\,\kappa} + \\ && C_{\gamma\,b}^{\,\,b} F_{k\,i}^{\,\,\kappa} + C_{\gamma\,b}^{\,\,c} F_{c\,i}^{\,\,\kappa} + C_{\gamma\,b}^{\,\,r} F_{r\,i}^{\,\,\kappa} - K_{i\,b}^{\,\,c} C_{\gamma\,c}^{\,\,\kappa} - K_{i\,b}^{\,\,r} L_{\gamma\,r}^{\,\,\kappa}. \end{array}$$

4 Ricci identities for ∇

From (2.6) it follows

$$(4.1) \qquad \nabla_X \nabla_Y Z = [(Z_{|\beta|}^{\gamma})Y^{\beta}]_{|\alpha} X^{\alpha} \delta_{\gamma} = (Z_{|\beta|\alpha}^{\gamma} Y^{\beta} + Z_{|\beta|}^{\gamma} Y_{|\alpha|}^{\beta}) X^{\alpha} \delta_{\gamma}.$$

From (2.6), (2.15) and (2.16) we obtain

(4.2)
$$\nabla_{[X,Y]}Z = Z^{\gamma}_{\beta}[X,Y]^{\beta}\delta_{\gamma} = A + B,$$

where

$$(4.3) A = Z^{\gamma}_{|\beta} [X^{\alpha} (\partial_{\alpha} Y^{\beta}) - Y^{\alpha} (\partial_{\alpha} X^{\beta})] \delta_{\gamma} =$$

$$= Z^{\gamma}_{|\beta} [X^{\alpha} Y^{\beta}_{|\alpha} - Y^{\alpha} X^{\beta}_{|\alpha} - (\Gamma^{\beta}_{\theta \alpha} - \Gamma^{\beta}_{\alpha \theta}) X^{\alpha} Y^{\theta}] \delta_{\gamma}$$

$$(4.4) B = X^{i}Y^{j}[Z^{\gamma}|_{c}K_{ij}^{c} + Z^{\gamma}|_{q}K_{ij}^{q}]\delta_{\gamma} + (X^{i}Y^{b} - Y^{i}X^{b})[Z^{\gamma}|_{c}K_{ib}^{c} + Z^{\gamma}|_{r}K_{ib}^{r}]\delta_{\gamma} + (X^{i}Y^{q} - Y^{i}X^{q})\delta_{\gamma} + X^{a}Y^{a}Z^{\gamma}|_{r}K_{ab}^{r}\delta_{\gamma}.$$

Taking into account (2.13) and (2.14) we obtain

$$(4.5) A + B = \left[Z_{\beta}^{\gamma} (X^{\alpha} Y_{\alpha}^{\beta} - Y^{\alpha} X_{\alpha}^{\beta}) - Z_{\kappa}^{\gamma} T_{\beta\alpha}^{\kappa} X^{\alpha} Y^{\beta} \right] \delta_{\gamma}.$$

From (4.1), (4.2) and (4.5) we obtain

$$(4.6) \qquad R(X,Y)Z = (Z_{|\beta|\alpha}^{\gamma} - Z_{|\alpha|\beta} + Z_{|\kappa}^{\gamma} T_{\beta\alpha}^{\kappa}) X^{\alpha} Y^{\beta} \delta_{\gamma} = \frac{1}{2} (Z_{|\beta|\alpha}^{\gamma} - Z_{|\alpha|\beta}^{\gamma} + Z_{|\kappa}^{\gamma} T_{\beta\alpha}^{\kappa}) (X^{\alpha} Y^{\beta} - Y^{\alpha} X^{\beta}) \delta_{\gamma}.$$

From (4.6) and (3.9) it follows:

Theorem 4.3. The Ricci equations for the generalized connection ∇ have the form:

$$(4.7) Z_{|\beta|\alpha}^{\gamma} - Z_{|\alpha|\beta}^{\gamma} + Z_{|\kappa}^{\gamma} T_{\beta\alpha}^{\kappa} = R_{\kappa\beta\alpha}^{\gamma} Z^{\kappa}.$$

(4.7) contains 3^3 types of Ricci equations, because each Greek index may be the element from one of the sets: $\{i, j, h, k, l\}, \{a, b, c, d, e\}, \{p, q, r, s, t\}.$

For $(\beta, \alpha) = (j, i)$ (4.7) becomes

$$\begin{split} Z_{|j|i}^{\gamma} - Z_{|i|j}^{\gamma} + Z_{|k}^{\gamma} T_{ji}^{k} + Z^{\gamma}|_{c} T_{ji}^{c} + Z^{\gamma}|_{p} T_{ji}^{p} &= \\ &= R_{kji}^{\gamma} Z^{k} + R_{cji}^{\gamma} Z^{c} + R_{pji}^{\gamma} Z^{p}, \end{split}$$

for $(\beta, \alpha) = (p, i)$ (4.7) takes the form

$$\begin{split} Z^{\gamma}\|_{p|i} - Z^{\gamma}_{|i}\|_{p} + Z^{\gamma}_{|k}T^{k}_{pi} + Z^{\gamma}|_{c}T^{c}_{pi} + Z^{\gamma}\|_{r}T^{r}_{pi} &= \\ &= R^{\gamma}_{k \ pi}Z^{k} + R^{\gamma}_{c \ pi}Z^{c} + R^{\gamma}_{r \ pi}Z^{r}, \ \text{e.t.c.} \end{split}$$

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